# HYPERMONOGENIC POLYNOMIALS 

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Abstract. Let $C \ell_{3}$ be the (universal) Clifford algebra generated by $e_{1}, e_{2}$ and $e_{3}$ satisfying $e_{i} e_{j}+e_{j} e_{i}=-2 \delta_{i j}, i, j=1,2,3$. The Dirac operator in $C \ell_{3}$ is defined by $D=\sum_{i=0}^{3} e_{i} \frac{\partial}{\partial x_{i}}$, where $e_{0}=1$. The modified Dirac operator is introduced by $M f=D f+2 \frac{Q^{\prime} f}{x_{3}}$, where' is the main involution and $Q f$ is given by the decomposition $f(x)=P f(x)+Q f(x) e_{3}$ with $\operatorname{Pf}(x), Q f(x) \in \mathbb{H}$. A continuously differentiable function $f: \Omega \rightarrow C \ell_{3}$ is called hypermonogenic in an open subset $\Omega$ of $R^{4}$, if $M f(x)=0$ outside the hyperplane $x_{3}=0$. We consider homogenous polynomials in various function spaces. In particular we collect results concerning differentiation and linear independency of the polynomials. We find a basis for homogeneous holomorphic Cliffordian polynomials of degree $m$.

## 1 Introduction

It is well know that the power function $x^{m}$ is not monogenic. In $\mathcal{C} \ell_{3}$ there are basically two ways to include the power function into the set of solutions: The hypermonogenic functions satisfying the equation $x_{3} M f=0$ or holomorphic Cliffordian functions satisfying the equation $\Delta D f=0$. Hypermonogenic functions are notably studied by H . Leutwiler and the first author for example in [2], [3], [4] and [5] while the holomorphic Cliffordian functions are studied by G. Laville and I. Ramadanoff in [7]. In addition, holomorphic Cliffordian function are in close connection with polyharmonic functions and iterated Dirac operators studied by L. Pernas in [8] and in the complex case by R. Ryan in [9].
L. Pernas has found out the dimension of the space of homogenous holomorphic Cliffordian polynomials of degree $m$ in [8], but his approach did not include a basis. It is known that the hypermonogenic functions are included in the space of holomorphic Cliffordian functions. As our main result we prove the surprising result that the polynomials $L_{m}^{\alpha}, T_{m}^{\beta}$ and $\frac{\partial T_{m+1}^{\gamma}}{\partial x_{3}}$ form a basis for the right module of homogeneous holomorphic Cliffordian polynomials of degree $m$. For this task, we first recall the function spaces of monogenic, hypermonogenic and holomorphic Cliffordian functions and give the results needed in the proof of our main theorem. We list some basic polynomials and their properties for the various function spaces. In particular, we consider recursive formulas, rules of differentiation and properties of linear independency for the polynomials.

## 2 Notations

As general references for the chapter we give [2], [3] and [5]. We consider the universal Clifford algebra $\mathcal{C} \ell_{3}$, that is the associative algebra over $\mathbb{R}$ generated by the elements $e_{1}, e_{2}$ and $e_{3}$ satisfying the relations

$$
e_{i}^{2}=-1
$$

and

$$
\begin{equation*}
e_{i} e_{j}=-e_{j} e_{i}, \tag{1}
\end{equation*}
$$

for $i, j=1,2,3$. Furthermore, we denote $e_{0}=1$. The general element of the algebra $\mathcal{C} \ell_{3}$ is of the form

$$
a=a_{0}+a_{1} e_{1}+a_{2} e_{2}+a_{3} e_{3}+a_{12} e_{12}+a_{13} e_{13}+a_{23} e_{23}+a_{123} e_{123},
$$

where the coefficients $a_{k}$ are real and the abbreviated notations are $e_{i} e_{j}=e_{i j}$ and $e_{1} e_{2} e_{3}=e_{123}$. In general, if $\alpha=\left\{\alpha_{1}, \ldots, \alpha_{j}\right\} \subseteq\{1,2,3\}$ and $\alpha_{1}<\alpha_{2}<$ $\ldots<\alpha_{j}$ we denote $e_{\alpha}=e_{\alpha_{1}} \cdots e_{\alpha_{j}}$, with $e_{\emptyset}=e_{0}$, and get the presentation

$$
a=\sum a_{\alpha} e_{\alpha} .
$$

We call the elements $x=x_{0}+x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}$, for $x_{i} \in \mathbb{R}$, paravectors. We identify the set of paravectors with the Euclidean space $\mathbb{R}^{4}$. By (1) it is clear that $\mathcal{C} \ell_{3}$ is not a commutative algebra. The elements $\alpha+\beta e_{123}$ with $\alpha, \beta \in \mathbb{R}$ commute with all elements of $\mathcal{C} \ell_{3}$.

In $\mathcal{C} \ell_{3}$ we define three involutions. The main involution ${ }^{\prime}: \mathcal{C} \ell_{3} \rightarrow \mathcal{C} \ell_{3}$ is the algebra isomorphism defined by $e_{0}=1$ and $e_{i}=-e_{i}$, for $i=1,2,3$. The reversion is an antiautomorphism ${ }^{*}: \mathcal{C} \ell_{3} \rightarrow \mathcal{C} \ell_{3}$ defined by $e_{i}^{*}=e_{i}$, for $i=0, \ldots, 3$ and $(a b)^{*}=b^{*} a^{*}$. The conjugation is the antiautomorphism ${ }^{-}: \mathcal{C} \ell_{3} \rightarrow \mathcal{C} \ell_{3}$ defined by $\bar{a}=\left(a^{*}\right)^{\prime}=\left(a^{\prime}\right)^{*}$.

We can embed the division algebra of quaternions $\mathbb{H}$ into the algebra $\mathcal{C} \ell_{3}$ by identifying $e_{1}$ with $i, e_{2}$ with $j$ and $e_{12}$ with $k$. Furthermore, we can decompose the algebra $\mathcal{C} \ell_{3}$ into two copies of $\mathbb{H}$ by writing

$$
\begin{aligned}
a & =a_{0}+a_{1} e_{1}+a_{2} e_{2}+a_{12} e_{12}+\left(a_{3}+a_{13} e_{1}+a_{23} e_{2}+a_{123} e_{12}\right) e_{3} \\
& =P a+Q a e_{3} .
\end{aligned}
$$

The relation defines the operators $P: \mathcal{C} \ell_{3} \rightarrow \mathbb{H}$ and $Q: \mathcal{C} \ell_{3} \rightarrow \mathbb{H}$ with the properties

$$
P^{2}=P, P Q=Q, Q P=0 \text { and } Q^{2}=0
$$

We define the involution ${ }^{\wedge}: \mathcal{C} \ell_{3} \rightarrow \mathcal{C} \ell_{3}$ by $\widehat{e_{3}}=-e_{3}, \widehat{e_{i}}=e_{i}$, for $i=0,1,2$ and $\widehat{a b}=\widehat{a b}$. Using this involution we obtain for any $a \in \mathcal{C} \ell_{3}$ the following formulas

$$
\begin{align*}
& P a=\frac{a-e_{3} a^{\prime} e_{3}}{2}=\frac{a+\widehat{a}}{2}  \tag{2}\\
& Q a=\frac{e_{3} a^{\prime}-a e_{3}}{2}=\frac{\widehat{a}-a}{2} e_{3} . \tag{3}
\end{align*}
$$

In proving the formulas (2) and (3) we use the identities

$$
a^{\prime} e_{3}=e_{3} \widehat{a} \text { and } e_{3} a^{\prime}=\widehat{a} e_{3},
$$

for arbitrary $a \in \mathcal{C} \ell_{3}$ and

$$
b^{\prime} e_{3}=e_{3} b \text { and } e_{3} b^{\prime}=b e_{3}
$$

for any $b \in \mathbb{H}$. In addition we can show that

$$
P\left(a^{\prime}\right)=(P a)^{\prime} \text { and } Q\left(a^{\prime}\right)=-(Q a)^{\prime} .
$$

In order to abbreviate the notations we set $(P a)^{\prime}=P^{\prime} a$ and $(Q a)^{\prime}=Q^{\prime} a$. For the $P$ - and $Q$-parts of a product we have

$$
\begin{align*}
& P(a b)=(P a) P b+(Q a) Q\left(b^{\prime}\right) \\
& Q(a b)=(P a) Q b+(Q a) P\left(b^{\prime}\right)  \tag{4}\\
& Q(a b)=a Q b+(Q a) b^{\prime} \tag{5}
\end{align*}
$$

For easy reference we recall some basic notations of multi-indexes. Let $\mathbb{N}_{0}=\{0,1,2, \ldots\}$. An element $\alpha=\left(\alpha_{0}, \alpha_{1}, \alpha_{2}, \alpha_{3}\right) \in \mathbb{N}_{0}^{4}$ is called a multiindex. For a multi-index $\alpha=\left(\alpha_{0}, \alpha_{1}, \alpha_{2}, \alpha_{3}\right) \in \mathbb{N}_{0}^{4}$ and a paravector $x_{0}+$ $x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}$ we have

$$
\begin{aligned}
x^{\alpha} & =x_{0}^{\alpha_{0}} x_{1}^{\alpha_{1}} x_{2}^{\alpha_{2}} x_{3}^{\alpha_{3}} \\
\alpha! & =\alpha_{0}!\alpha_{1}!\alpha_{2}!\alpha_{3}!(\text { factorial }) \\
|\alpha| & =\alpha_{0}+\alpha_{1}+\alpha_{2}+\alpha_{3} \text { (length of } \alpha \text { ) } \\
\binom{m}{\alpha} & =\frac{m!}{\alpha!}=\frac{m!}{\alpha_{0}!\alpha_{1}!\alpha_{2}!\alpha_{3}!}, \text { if }|\alpha|=m .
\end{aligned}
$$

We denote by $\varepsilon_{i}$ the multi-index $\left(\alpha_{0}, \alpha_{1}, \alpha_{2}, \alpha_{3}\right)$, with $\alpha_{i}=1$ and $|\alpha|=1$.

## 3 Function spaces

Let $\Omega$ be an open subset of $\mathbb{R}^{4}$. We define the left Dirac operator for a mapping $f: \Omega \rightarrow \mathcal{C} \ell_{3}$ with continuously differentiable components by

$$
D_{l} f=\sum_{i=0}^{3} e_{i} \frac{\partial f}{\partial x_{i}}
$$

and the right Dirac operator by

$$
D_{r} f=\sum_{i=0}^{3} \frac{\partial f}{\partial x_{i}} e_{i}
$$

The functions satisfying $D_{l} f=0$ are called left monogenic and the functions satisfying $D_{r} f=0$ are called right monogenic.

Since the properties $D_{l} f=0$ and $D_{r} f^{*}=0$ are equivalent, it is sufficient to consider only the left operator, the properties of the right one being analogous. In particular this is true for paravector valued functions, since in this
case $f=f^{*}$. In what follows, we abbreviate $D_{l}=D$ and call $D$ the Dirac operator. We define the operator $\bar{D}$ by

$$
\bar{D}=\sum_{i=0}^{3} \overline{e_{i}} \frac{\partial f}{\partial x_{i}} .
$$

A simple calculation shows that we can decompose the Laplace-operator in $\mathbb{R}^{4}$ as

$$
\Delta=\frac{\partial^{2}}{\partial x_{0}^{2}}+\frac{\partial^{2}}{\partial x_{1}^{2}}+\frac{\partial^{2}}{\partial x_{2}^{2}}+\frac{\partial^{2}}{\partial x_{3}^{2}}=D \bar{D}=\bar{D} D
$$

and therefore monogenic functions are harmonic. However, there are functions, for example $f(x)=x$ that are harmonic but are not monogenic.

The fact that the power function $F(x)=x^{m}$ is not monogenic even if $m=1$ was the main reason for H. Leutwiler and S.-L. Eriksson to introduce the modified Dirac operator $M$ defined for functions $f \in \mathcal{C}^{1}\left(\Omega, \mathcal{C} \ell_{3}\right)$ by

$$
M f=D+\frac{2}{x_{3}} Q^{\prime} f
$$

and the operator $\bar{M}$ by

$$
\bar{M} f=\bar{D}-\frac{2}{x_{3}} Q^{\prime} f .
$$

Similarly as in the case of monogenic functions we study only the left operator.

A function $f: \Omega \rightarrow \mathcal{C} \ell_{3}$ is called hypermonogenic, if $f \in \mathcal{C}^{1}(\Omega)$ and $x_{3} M f=0$ for all $x \in \Omega$. Paravector valued hypermonogenic functions are called $H$-solutions. The hypermonogenic functions are closely related to the hyperbolic metric $d s^{2}=\frac{1}{x_{2}^{3}}\left(x_{0}^{2}+x_{1}^{2}+x_{2}^{2}+x_{3}^{2}\right)$ and therefore we consider the hyperbolic Laplace operator $\Delta_{H}=\Delta-\frac{2}{x_{3}} \frac{\partial}{\partial x_{3}}$ associated to this metric. The functions satisfying $\Delta_{H}=0$ are called hyperbolic harmonic functions. The definition of hypermonogenic functions can be written using the $P$ - and $Q$ parts.

Lemma 1 ([3, Proposition 3]) Let $\Omega$ be an open subset of $\mathbb{R}^{4}$ and $f: \Omega \rightarrow$ $\mathcal{C} \ell_{3}$ be a mapping with continuous partial derivatives. The equation $M f=0$ is equivalent with the system of equations

$$
\begin{align*}
x_{3}\left(D_{2}(P f)-\frac{\partial Q^{\prime} f}{\partial x_{3}}\right)+2 Q^{\prime} f & =0,  \tag{6}\\
D_{2}(Q f)+\frac{\partial P^{\prime} f}{\partial x_{3}} & =0, \tag{7}
\end{align*}
$$

where $D_{2} f=\sum_{i=0}^{2} e_{i} \frac{\partial f}{\partial x_{i}}$.

The equations (6) and (7) have some immediate consequences (see [2, Lemma 10]).

Lemma 2 Let $f$ be hypermonogenic on $\Omega \subset \mathbb{R}^{4}$ with $\omega=\Omega \cap \mathbb{R}^{3} \neq \emptyset$. Then on $\omega$ we have

$$
\begin{array}{r}
Q f(\cdot, 0)=0, \\
D_{2} \operatorname{Pf}(\cdot, 0)=-\frac{\partial Q^{\prime} f}{\partial x_{3}}(\cdot, 0), \\
\frac{\partial P f}{\partial x_{3}}(\cdot, 0)=0 . \tag{10}
\end{array}
$$

Proof. The proof of (8) is just to evaluate (6) at $x_{3}=0$. Writing (6) as

$$
D_{2} P f-\frac{\partial Q^{\prime} f}{\partial x_{3}}+2 \frac{Q^{\prime} f}{x_{3}}=0
$$

and letting $x_{3} \rightarrow 0$ yield

$$
D_{2} P f(\cdot, 0)-\frac{\partial Q^{\prime} f}{\partial x_{3}}(\cdot, 0)+2 \frac{\partial Q^{\prime} f}{\partial x_{3}}(\cdot, 0)=0,
$$

since $f$ has continuous partial derivatives. Thus

$$
\frac{\partial Q^{\prime} f}{\partial x_{3}}(\cdot, 0)=D_{2} P f(\cdot, 0)
$$

and we have (9). Combining (9) and (7) we get (10).
Lemma 3 The $P$ - and $Q$-parts of a hypermonogenic function $f$ satisfy the equations

$$
\begin{array}{r}
x_{3} \Delta P f-2 \frac{\partial P f}{\partial x_{3}}=0 \\
x_{3}^{2} \Delta Q f-2 x_{3} \frac{\partial Q f}{\partial x_{3}}+2 Q f=0 . \tag{12}
\end{array}
$$

Proof. Choose $k=2$ in [6, Lemma 2].
The previous Lemma states that the $P$-part of a hypermonogenic function is a hyperbolic harmonic function and the $Q$-component is an eigenfunction of the Laplace-Beltrami operator $x_{3}^{2} \Delta_{H}$ corresponding to the eigenvalue -2 . Furthermore, we obtain for the derivative $\frac{\partial h}{\partial x_{3}}$ of a hyperbolic harmonic function the following result.

Lemma 4 If $h$ is a hyperbolic harmonic function then $\frac{\partial h}{\partial x_{3}}$ is an eigenfunction of the Laplace-Beltrami operator $x_{3}^{2} \Delta_{H}$ corresponding to the eigenvalue -2 .

Proof. Suppose $\Delta_{H} h=0$. Differentiating with respect to the variable $x_{3}$ yields

$$
0=\frac{\partial}{\partial x_{3}}\left(\Delta h-\frac{2}{x_{3}} \frac{\partial}{\partial x_{3}} h\right)=\Delta \frac{\partial h}{\partial x_{3}}-\frac{2}{x_{3}} \frac{\partial^{2} h}{\partial x_{3}^{2}}+\frac{2}{x_{3}^{2}} \frac{\partial h}{\partial x_{3}}
$$

and the result follows by multiplying by $x_{3}^{2}$.
Hypermonogenic functions form a right vectorspace over the quaternions and the derivatives $\frac{\partial f}{\partial x_{i}}$ of a hypermonogenic function $f$ are hypermonogenic for $i=0,1,2$. But multiplication by $e_{3}$ and differentiation with respect to the variable $x_{3}$ do not preserve hypermonogenicity.

Lemma 5 If $f$ is a hypermonogenic function, then the function $f e_{3}$ is hypermonogenic if and only if $f=0$.

Proof. Assume that $f$ and $f e_{3}$ are hypermonogenic. By definition

$$
\begin{equation*}
D f+\frac{2}{x_{3}} Q^{\prime} f=0 \tag{13}
\end{equation*}
$$

and

$$
\begin{equation*}
D\left(f e_{3}\right)+\frac{2}{x_{3}} Q^{\prime}\left(f e_{3}\right)=0 . \tag{14}
\end{equation*}
$$

Since $D\left(f e_{3}\right)=(D f) e_{3}$ and by (4) $Q\left(f e_{3}\right)=P f$ multiplying (13) by $-e_{3}$ from the right and adding up with (14) yields

$$
-\frac{2}{x_{3}}\left(Q^{\prime} f\right) e_{3}+\frac{2}{x_{3}} P^{\prime} f=0
$$

and thus $\frac{2}{x_{3}} Q f e_{3}+\frac{2}{x_{3}} P f=\frac{2}{x_{3}} f=0$. If $f=0$ then trivially $f e_{3}$ is hypermonogenic.
Lemma 6 If $f$ is a hypermonogenic function, then the function $\frac{\partial f}{\partial x_{3}}$ is hypermonogenic if and only if $Q f=0$.

Proof. If $Q f=0$ and $f$ is hypermonogenic then $D f=0$ and thus $\frac{\partial}{\partial x_{3}}(D f)=D\left(\frac{\partial}{\partial x_{3}} f\right)=0$ and $\frac{\partial}{\partial x_{3}} f$ is hypermonogenic, since $Q\left(\frac{\partial}{\partial x_{3}} f\right)=0$.

Assume that $f$ and $\frac{\partial}{\partial x_{3}} f$ are hypermonogenic. Then $\frac{\partial}{\partial x_{3}}\left(D f+\frac{2}{x_{3}} Q^{\prime} f\right)=$ 0 and $D\left(\frac{\partial}{\partial x_{3}} f\right)+\frac{2}{x_{3}} Q^{\prime}\left(\frac{\partial}{\partial x_{3}} f\right)=0$. Subtracting the equations gives $\frac{2}{x_{3}^{2}} Q^{\prime} f=$ 0 and therefore $Q f=0$.

Lemma 6 is an equivalent form of the following result.

Lemma 7 ([2, Theorem 4]) If $f$ is a hypermonogenic function then the function $\frac{\partial f}{\partial x_{3}}$ is hypermonogenic if and only if $\frac{\partial f}{\partial x_{3}}=0$.

Combining multiplication by $e_{3}$ and differentiation with respect to the variable $x_{3}$ yields a hypermonogenic function.

Lemma 8 ([4, Theorem 3]) If $f$ is a hypermonogenic function then the function $g$ defined by

$$
g=\frac{\partial f}{\partial x_{3}} e_{3}+\frac{2 Q f}{x_{3}}
$$

is hypermonogenic.
Another way to include the power function into the set of solutions is to consider the holomorphic Cliffordian functions defined by the condition $D \Delta f=0$. The holomorphic Cliffordian functions are studied for example in [7]. The spaces of monogenic, harmonic and hypermonogenic functions are included in the space of holomorphic Cliffordian functions.

## 4 Polynomial solutions

First we consider the monogenic polynomials. We note that $D x=-2 \neq$ 0 and therefore we cannot use the polynomials $x^{k}$ to construct monogenic polynomial solutions. Therefore the homogeneous monogenic polynomials of degree $m$ denoted $F_{m}^{\alpha}$ and called the Fueter-polynomials, (see for example [1], [10] or [11]) are defined by

$$
\begin{equation*}
F_{m}^{\alpha}(x)=\sum z_{\sigma_{1}} z_{\sigma_{2}} \cdots z_{\left.\sigma\right|_{\alpha} \mid} \tag{15}
\end{equation*}
$$

where the sum is over all different permutations $\sigma=\left(\sigma_{1}, \ldots, \sigma_{|\alpha|}\right)$ of $|\alpha|$ elements containing $\alpha_{1}$ 1's $\alpha_{2}$ 2's and $\alpha_{3}$ 3's. The variables $z_{1}=\left(x_{0} e_{1}-x_{1}\right)$, $z_{2}=\left(x_{0} e_{2}-x_{2}\right)$ and $z_{3}=\left(x_{0} e_{3}-x_{3}\right)$ in (15) are called the hypercomplex variables. For the Fueter-polynomials it holds (see [11, Lemma 1.6]).

Theorem 9 ([11], Lemma 1.6) The polynomials $F_{m}^{\alpha}$ are monogenic and linearly independent over $\mathcal{C} \ell_{3}$.

The Fueter-polynomials satisfy the recursion relation

$$
F_{m}^{\alpha}(x)=z_{1} F_{m}^{\alpha-\varepsilon_{1}}(x)+z_{2} F_{m}^{\alpha-\varepsilon_{2}}(x)+z_{3} F_{m}^{\alpha-\varepsilon_{3}}(x)
$$

and the derivatives of the Fueter-polynomials are given by

$$
\frac{\partial F_{m}^{\alpha}}{\partial x_{k}}=|\alpha| F_{m-1}^{\alpha-\varepsilon_{k}}
$$

(see for example [11] for the proofs).
Next we consider homogeneous hypermonogenic polynomials of degree $m$. The definitions and results are from [5] if not otherwise stated.

Definition 10 Let $\alpha=\left(\alpha_{1}, \alpha_{2}\right) \in \mathbb{N}_{0}^{2}$. The elementary $H$-polynomial $E_{m}^{\alpha}$ is defined by

$$
E_{m}^{\alpha}(x)=\sum_{\left(\sigma_{0}, \ldots, \sigma_{m}\right) \in \sigma} \sigma_{0} x \sigma_{1} \cdots x \sigma_{m}
$$

where $\sigma$ is the set of all permutations of $m+1$ elements containing $\alpha_{1}$ elements equal to $e_{1}$ and $\alpha_{2}$ elements equal to $e_{2}$ and the rest equal to 1 . We set $E_{0}^{(0,0)}(x)=1$. If $|\alpha|>m+1$ or $\alpha_{i}<0$, we set $E_{m}^{\alpha}(x)=0$.

Definition 11 Let $\alpha=\left(\alpha_{1}, \alpha_{2}\right) \in \mathbb{N}_{0}^{2}$. The elementary H-polynomial $L_{m}^{\alpha}$ is defined by

$$
L_{m}^{\alpha}(x)=\sum_{\left(\sigma_{0}, \ldots, \sigma_{m}\right) \in \sigma} z_{\sigma_{1}} z_{\sigma_{2}} \cdots z_{\sigma_{m+|\alpha|}},
$$

where the sum is over all permutations of elements $z_{\sigma_{1}}, z_{\sigma_{2}}, \ldots, z_{\sigma_{m+|\alpha|}}$ containing $m$ elements equal to $x, \alpha_{1}$ equal to $e_{1}$ and $\alpha_{2}$ equal to $e_{2}$. We set $L_{0}^{(0,0)}(x)=1$ and $L_{m}^{\alpha}(x)$, if $\alpha_{1}<0$ or $\alpha_{2}<0$.

The polynomials $E_{m}^{\alpha}$ and $L_{m}^{\alpha}$ satisfy the following recursion formulas (see [11]).

Lemma 12 Let $\alpha \in \mathbb{N}_{0}^{2}$ and $m$ be a non-negative integer. Then

$$
\begin{equation*}
E_{m}^{\alpha}(x)=x E_{m-1}^{\alpha}(x)+e_{1} x E_{m-1}^{\alpha-\varepsilon_{1}}(x)+e_{2} x E_{m-1}^{\alpha-\varepsilon_{2}}(x) \tag{16}
\end{equation*}
$$

and

$$
\begin{equation*}
L_{m}^{\alpha}(x)=x L_{m-1}^{\alpha}(x)+e_{1} L_{m}^{\alpha-\varepsilon_{1}}(x)+e_{2} L_{m}^{\alpha-\varepsilon_{2}}(x) . \tag{17}
\end{equation*}
$$

Since the mapping

$$
x \rightarrow \frac{1}{\alpha!} \frac{\partial^{|\alpha|} x^{m+|\alpha|}}{\partial x^{\alpha}}
$$

satisfies the recursion formula (17) with the same initial values as $L_{m}^{\alpha}$, we obtain the second definition for the polynomials $L_{m}^{\alpha}$.

Definition 13 Let $\alpha \in \mathbb{N}_{0}^{2}$ and $m$ be a non-negative integer. Then

$$
\begin{equation*}
L_{m}^{\alpha}=\frac{1}{\alpha!} \frac{\partial^{|\alpha|} x^{m+|\alpha|}}{\partial x^{\alpha}} . \tag{18}
\end{equation*}
$$

The polynomials $L_{m}^{\alpha}$ are explicitly known (see [5, Theorem 19]).

Theorem 14 If $\alpha=\left(\alpha_{1}, \alpha_{2}\right) \in \mathbb{N}_{0}^{2}$ and $m \in \mathbb{N}$, then

$$
L_{m}^{\alpha}(x)=\sum_{|\beta|=m}\binom{m+|\alpha|}{\alpha, \beta} c(\beta+\alpha) x^{\beta}
$$

where the coefficients $c(\gamma)$ for $\gamma=\left(\gamma_{0}, \widetilde{\gamma}\right), \gamma_{0} \in \mathbb{N}_{0}$ and $\widetilde{\gamma}=\left(\gamma_{1}, \gamma_{2}, \gamma_{3}\right) \in \mathbb{N}_{0}^{3}$ are given by
$c(\gamma)= \begin{cases}\left.\frac{\binom{|\widetilde{\gamma}| / 2}{\widetilde{\gamma} / 2}}{(|\widetilde{\gamma}|}\right)(-1)^{(|\widetilde{\gamma}| / 2)}, & \text { if } \widetilde{\gamma} \text { is even, } \\ \left.\begin{array}{ll}\widetilde{\gamma}\end{array}\right) \\ \frac{\binom{|\widetilde{\gamma}|-1) / 2}{\left(\widetilde{\gamma}-\varepsilon_{i}\right) / 2}}{\binom{|\widetilde{\gamma}|}{\widetilde{\gamma}}}(-1)^{(||\widetilde{\gamma}|-1) / 2)} e_{i}, & \text { if } i=1,2,3 \text { and } \widetilde{\gamma}-\varepsilon_{i} \text { is even, } \\ 0, & \text { otherwise. }\end{cases}$
Theorem 14 has an immediate consequence that we list as a Lemma for the proof of our main result Theorem 26.

Lemma 15 Let $\alpha \in \mathbb{N}_{0}^{2}$ and $m \in \mathbb{N}$. Then

$$
\frac{\partial^{k} Q L_{m}^{\alpha}}{\partial x_{3}^{k}}(\cdot, 0)=0
$$

for all even $k \in \mathbb{N}$.
Proof. By Theorem $14 e_{3}$ appears in $c(\beta+\alpha)$ only when $\beta_{3}-1$ is even. Thus $Q L_{m}^{\alpha}$ is odd with respect to the variable $x_{3}$. Differentiating an even number of times with respect to $x_{3}$ yields terms with odd powers of $x_{3}$, which vanish when evaluated at $x_{3}=0$.

The derivative of the polynomial $E_{m}^{\alpha}$ is given by

$$
\begin{aligned}
& \frac{\partial E_{m}^{\alpha}}{\partial x_{i}}=\left(\alpha_{i}+1\right) E_{m-1}^{\alpha+\varepsilon_{i}}-\left(2 m-\alpha_{i}+1\right) E_{m-1}^{\alpha-\varepsilon_{i}}+\left(\alpha_{i}+1\right) E_{m-1}^{\alpha+\varepsilon_{i}-2 \varepsilon_{2}} \\
& \frac{\partial E_{m}^{\alpha}}{\partial x_{0}}=(m+|\alpha|) E_{n-1}^{\alpha}-(m-|\alpha|+2) \sum_{i=1}^{2} E_{m-1}^{\alpha-2 \varepsilon_{i}},
\end{aligned}
$$

for $i \in\{1,2\}$ and $|\alpha| \geq 2$ (see [5]) while the derivatives of polynomial $L_{m}^{\alpha}$ with $|\alpha| \geq 2$ satisfy the equations

$$
\frac{\partial L_{m}^{\alpha}}{\partial x_{0}}=(m+|\alpha|) L_{m-1}^{\alpha}
$$

and

$$
\frac{\partial L_{m}^{\alpha}}{\partial x_{k}}=\left(\alpha_{k}+1\right) L_{m-1}^{\alpha+\varepsilon_{k}}
$$

for $k \in\{1,2\}$ (see for example [5]). The derivatives of the polynomials $L_{m}^{\alpha}$ with respect to $x_{3}$ can be found out differentiating the presentation (18). In particular we get

Proposition 16 For polynomials $L_{m}^{\alpha}$ with $|\alpha|=m$

$$
\frac{\partial Q L_{m}^{\alpha}}{\partial x_{3}}(\cdot, 0)=\frac{1}{\alpha!} \frac{\partial^{|\alpha|}}{\partial x^{\alpha}} \sum_{l=1}^{m}(-1)^{m-l}\binom{2 m}{2 l-1} x_{0}^{2 l-1}\left(x_{1}^{2}+x_{2}^{2}\right)^{m-l} .
$$

Proof. Since $x_{0}$ is real we get by the binomial theorem

$$
\begin{array}{r}
x^{2 m}=\left(x_{0}+x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}\right)^{2 m}=\sum_{\substack{k=0}}^{2 m}\binom{2 m}{k} x_{0}^{k}\left(x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}\right)^{2 m-k} \\
=\sum_{\substack{k=0 \\
k \text { even }}}^{2 m}\binom{2 m}{k} x_{0}^{k}\left(x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}\right)^{2 m-k}+\sum_{\substack{k=0 \\
k \text { odd }}}^{2 m-1}\binom{2 m}{k} x_{0}^{k}\left(x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}\right)^{2 m-k} .
\end{array}
$$

Since $\left(x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}\right)^{2 l}=(-1)^{l}\left(x_{1}^{2}+x_{2}^{2}+x_{3}^{2}\right)^{l}$ is real the $Q$ part of $x^{2 m}$ comes out from the odd part of the previous sum. Thus writing $k=2 l-1$ we obtain

$$
\begin{array}{r}
Q x^{2 m}=Q\left(\sum_{l=1}^{m}\binom{2 m}{2 l-1} x_{0}^{2 l-1}\left(x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}\right)^{2 m-2 l+1}\right) \\
=Q\left(\sum_{l=1}^{m}\binom{2 m}{2 l-1} x_{0}^{2 l-1}(-1)^{m-l}\left(x_{1}^{2}+x_{2}^{2}+x_{3}^{2}\right)^{m-l}\left(x_{1} e_{1}+x_{2} e_{2}+x_{3} e_{3}\right)\right) \\
=\sum_{l=1}^{m}\binom{2 m}{2 l-1} x_{0}^{2 l-1}(-1)^{m-l}\left(x_{1}^{2}+x_{2}^{2}+x_{3}^{2}\right)^{m-l} x_{3}
\end{array}
$$

and differentiating with respect to $x_{3}$ yields

$$
\begin{gathered}
\frac{\partial Q x^{2 m}}{\partial x_{3}}=\sum_{l=1}^{m}\binom{2 m}{2 l-1} x_{0}^{2 l-1}(-1)^{m-l}\left(x_{1}^{2}+x_{2}^{2}+x_{3}^{2}\right)^{m-l} \\
+\sum_{l=1}^{m-1}\binom{2 m}{2 l-1} x_{0}^{2 l-1}(-1)^{m-l}(m-l)\left(x_{1}^{2}+x_{2}^{2}+x_{3}^{2}\right)^{m-l-1} 2 x_{3}^{2}
\end{gathered}
$$

and therefore

$$
\begin{equation*}
\frac{\partial Q x^{2 m}}{\partial x_{3}}(\cdot, 0)=\sum_{l=1}^{m}(-1)^{m-l}\binom{2 m}{2 l-1} x_{0}^{2 l-1}\left(x_{1}^{2}+x_{2}^{2}\right)^{m-l} . \tag{19}
\end{equation*}
$$

Since $\mathbb{R}^{4}$ is of even dimension, we need some additional polynomials, called the $T$-polynomials, to construct a basis for the $\mathbb{H}$-module of homogeneous polynomial $H$-solutions (see [5, Definition 4]). The homogeneous polynomial $T_{m}^{\alpha}$ may be characterized as follows.

Lemma 17 ([6, Lemma 9]) Let $\alpha \in \mathbb{N}_{0}^{3}$, with $|\alpha|=m-2$. Then

$$
\frac{\partial^{\alpha} T_{m}^{\alpha}}{\partial x^{\alpha}}=\alpha!x_{3}^{2} e_{3}
$$

and

$$
\frac{\partial^{2} T_{m}^{\alpha}}{\partial x_{3}^{2}}(x)=2 x^{\alpha} e_{3}
$$

for any $x$ with $x_{3}=0$.
The $T_{m}^{a}$-polynomials are explicitly known (see [11, Theorem 2.14]). The part $P T_{m}^{\alpha}$ has the explicit presentation

$$
\begin{equation*}
P T_{m}^{\alpha}=\sum_{i=0}^{2}\left(\left(-e_{i}^{2}\right) \sum_{\beta=0}^{\left[\frac{\alpha}{2}\right]} d_{\beta, i} x^{\alpha-2 \beta-\varepsilon_{i}} x_{3}^{2|\beta|+3}\right) e_{i}, \tag{20}
\end{equation*}
$$

for some real coefficients $d_{\beta, i}$ while $Q T_{m}^{\alpha}$ has the explicit presentation

$$
\begin{equation*}
Q T_{m}^{\alpha}=\sum_{\beta=0}^{\left[\frac{\alpha}{2}\right]} d_{\beta} x^{\alpha-2 \beta} x_{3}^{2|\beta|+2} \tag{21}
\end{equation*}
$$

with some real coefficients $d_{\beta}$. The above presentations give us the next result for the proof of our main theorem.

Lemma 18 For any odd $k \in \mathbb{N}_{0}$

$$
\begin{equation*}
\frac{\partial^{k} Q T_{m}^{\alpha}}{\partial x_{3}^{k}}(\cdot, 0)=0 \tag{22}
\end{equation*}
$$

and for any even $l \in \mathbb{N}_{0}$

$$
\begin{equation*}
\frac{\partial^{l} P T_{m}^{\alpha}}{\partial x_{3}^{l}}(\cdot, 0)=0 \tag{23}
\end{equation*}
$$

Proof. By (21) $Q T_{m}^{\alpha}$ consists of terms containing only even powers of $x_{3}$ with degree at least 2 and by (20) $P T_{m}^{\alpha}$ consists of terms containing only odd powers of $x_{3}$ with degree at least 3 thus after differentiation in both cases $x_{3}$ remains in all which vanish evaluating at $x_{3}=0$.

Holomorphic Cliffordian polynomials are defined for a multi-index $\alpha \in \mathbb{N}_{0}^{4}$ by

$$
\begin{equation*}
P^{\alpha}(x)=\sum_{\sigma \in \sigma(\alpha)} e_{\sigma_{1}} x e_{\sigma_{2}} x \cdots e_{\sigma_{|\alpha|-1}} x e_{\sigma_{|\alpha|}}, \tag{24}
\end{equation*}
$$

where the sum is over all distinguishable permutations $\sigma=\left(\sigma_{1}, \sigma_{2}, \ldots, \sigma_{|\alpha|}\right)$ of $|\alpha|$ elements of the set $\{0,1,2,3\}$ with $\alpha_{k}$ elements equal to $k(k=0, \ldots, 3)$. The polynomial $P^{\alpha}(x)$ is a homogenous polynomial of degree $|\alpha|-1$. The polynomials $P^{\alpha}$ satisfy the same recursion formulas as the polynomials $E_{n}^{\alpha}$. Furthermore the differentiation rules are the same as in the case of the polynomials $E_{n}^{\alpha}$ (see [7],[11]).

## 5 Linear independence of the homogenous polynomials

In this chapter we state results concerning the linear independence of various classes of polynomials. The main result is Theorem 26.

The monogenic polynomials $F_{m}^{\alpha}$ are linearly independent over $\mathcal{C} \ell_{3}$ by Theorem 9. We recall the result

Theorem 19 ([5, Theorem 25]) The basis of the right $\mathbb{H}$-module generated by the homogeneous polynomial $H$-solutions of degree $m$ is

$$
\left\{L_{m}^{\alpha}\left|\alpha \in \mathbb{N}_{0}^{2},|\alpha| \leq m\right\} \cup\left\{T_{m}^{\beta}\left|\beta \in \mathbb{N}_{0}^{3}, \quad\right| \beta \mid=m-2\right\} .\right.
$$

By Theorem 19 the polynomials $L_{m}^{\alpha}$ and $T_{m}^{\beta}$ are right linearly independent over $\mathbb{H}$, but even stronger result holds. It is convenient to denote

$$
\begin{aligned}
& \Lambda_{0}^{m}=\left\{\alpha \in \mathbb{N}_{0}^{2}| | \alpha \mid \leq m\right\}, \\
& \Lambda_{1}^{m}=\left\{\alpha \in \mathbb{N}_{0}^{3}| | \alpha \mid=m-1\right\}, \\
& \Lambda_{2}^{m}=\left\{\alpha \in \mathbb{N}_{0}^{3}| | \alpha \mid=m-2\right\}, \\
& \Lambda_{3}^{m}=\left\{\alpha \in \mathbb{N}_{0}^{2}| | \alpha \mid=m\right\} .
\end{aligned}
$$

Theorem 20 The polynomials $L_{m}^{\alpha}$, with $\alpha \in \Lambda_{0}^{m}$ and $T_{m}^{\beta}$, with $\beta \in \Lambda_{2}^{m}$ are right linearly independent over $\mathcal{C l}_{3}$ and form a basis of the right $\mathrm{Cl}_{3}$-module generated by the homogeneous polynomial $H$-solutions of degree $m$.

Proof. It suffices to show that the polynomials are right linearly independent over $\mathcal{C} \ell_{3}$. Assume that

$$
\sum_{\alpha \in \Lambda_{0}^{m}} L_{m}^{\alpha} a(\alpha)+\sum_{\beta \in \Lambda_{2}^{m}} T_{m}^{\beta} b(\alpha)=0
$$

for some coefficients $a(\alpha), b(\beta) \in \mathcal{C} \ell_{3}$. Decomposing the coefficients into their $P$ - and $Q$-parts yields

$$
\begin{equation*}
\sum L_{m}^{\alpha} P a(\alpha)+\sum L_{m}^{\alpha} Q a(\alpha) e_{3}+\sum T_{m}^{\beta} P b(\beta)+\sum T_{m}^{\beta} Q b(\beta) e_{3}=0 \tag{25}
\end{equation*}
$$

Since $\sum L_{m}^{\alpha} P a(\alpha)+\sum T_{m}^{\beta} P b(\beta)$ is a hypermonogenic function, also

$$
\sum L_{m}^{\alpha} Q a(\alpha) e_{3}+\sum T_{m}^{\beta} Q b(\beta) e_{3}
$$

must be hypermonogenic and by Lemma 5

$$
\sum L_{m}^{\alpha} Q a(\alpha)+\sum T_{m}^{\beta} Q b(\beta)=0
$$

By Theorem 19 we know that the polynomials $L_{m}^{\alpha}$ and $T_{m}^{\beta}$ are right linearly independent over $\mathbb{H}$ and therefore $Q a(\alpha)=0$ and $Q b(\beta)=0$ for all $\alpha \in \Lambda_{0}^{m}$ and $\beta \in \Lambda_{2}^{m}$. Substituting the zero coefficients into (25) yields $P a(\alpha)=$ $0=\operatorname{Pb}(\beta)$. Thus $a(\alpha)=0=b(\beta)$ for all $\alpha \in \Lambda_{0}^{m}$ and $\beta \in \Lambda_{2}^{m}$ and the polynomials $L_{m}^{\alpha}$ and $T_{m}^{\beta}$ are right linearly independent over $\mathcal{C} \ell_{3}$.

From the previous proof we obtain a more general result.
Proposition 21 Any set of hypermonogenic polynomials that is right linearly independent over $\mathbb{H}$ is right linearly independent over $\mathcal{C} \ell_{3}$ as well.

Laville and Ramadanoff have proved in [7] that the holomorphic Cliffordian polynomials $P^{\alpha}$ in (24) form a generating set for the homogeneous polynomials satisfying the equation $D \Delta f=0$. However, the polynomials $P^{\alpha}$ are not linearly independent (see for example [11, Example 3.4.]). The dimension of the space of homogeneous holomorphic Cliffordian polynomials of degree $m$ is

$$
\begin{equation*}
1+3 \frac{m(m+1)}{2} \tag{26}
\end{equation*}
$$

as stated in [8, Theorem 14]. We know by Lemma 5 that the polynomials $L_{m}^{\alpha} e_{3}$ and $T_{m}^{\beta} e_{3}$ are not hypermonogenic, but they are holomorphic Cliffordian. In addition they are linearly independent over $\mathcal{C} \ell_{3}$, when $\alpha \in \Lambda_{0}^{m}$ and $\beta \in \Lambda_{2}^{m}$. We try to extend the set

$$
\left\{L_{m}^{\alpha} \mid \alpha \in \Lambda_{0}^{m}\right\} \cup\left\{T_{m}^{\beta} \mid \beta \in \Lambda_{2}^{m}\right\}
$$

in order to find a basis for the homogeneous polynomials of degree $m$ satisfying the equation $D \Delta f=0$.

For technical reasons we define a set of new polynomials $S_{m}^{\alpha}$.
Lemma 22 For every $\alpha=\left(\alpha_{0}, \alpha_{1}, \alpha_{2}\right) \in \mathbb{N}_{0}^{3}$ with $|\alpha|=m-1$ there exists a homogeneous polynomial $H$-solution of degree $m$ denoted by $S_{m}^{\alpha}$ satisfying the properties

$$
\frac{\partial Q S_{m}^{\alpha}}{\partial x_{3}}(\cdot, 0)=x^{\alpha} \text { and } \frac{\partial^{2} Q S_{m}^{\alpha}}{\partial x_{3}^{2}}(\cdot, 0)=0 .
$$

Proof. If $S_{m}^{\alpha}$ is hypermonogenic, the function

$$
f=\frac{Q S_{m}^{\alpha}}{x_{3}}
$$

is harmonic. Note that the harmonicity of the function $f$ implies that $f$ is determined by the values $f(\cdot, 0)$ and $\frac{\partial f}{\partial x_{3}}(\cdot, 0)$ (see for example [11, Lemma 1.3]). Since $Q S_{m}^{\alpha}$ is odd and thus $f$ even, we only need the values of $f$ in the plane $x_{3}=0$. Since $f$ is a polynomial $f$ is smooth enough for us to obtain

$$
f(\cdot, 0)=\lim _{x_{3} \rightarrow 0} \frac{Q S_{m}^{\alpha}}{x_{3}}(x)=\frac{\partial Q S_{m}^{\alpha}}{\partial x_{3}}(\cdot, 0)=x^{\alpha},
$$

we get

$$
\frac{Q S_{m}^{\alpha}}{x_{3}}=x^{\alpha}+\sum_{k=0}^{\left[\frac{m-1}{2}\right]} \frac{(-1)^{k} \Delta_{3}^{k} x^{\alpha} x_{3}^{2 k}}{(2 k)!}
$$

where $\Delta_{3}=\frac{\partial^{2}}{\partial x_{0}^{2}}+\frac{\partial^{2}}{\partial x_{1}^{2}}+\frac{\partial^{2}}{\partial x_{2}^{2}}$ is the Laplacian in $\mathbb{R}^{3}$. By [3, Corollary 16] the polynomial $S_{m}^{\alpha}$ is determined by the $Q$-part

$$
Q S_{m}^{\alpha}=x^{\alpha} x_{3}+x_{3} \sum_{k=0}^{\left[\frac{m-1}{2}\right]} \frac{(-1)^{k} \Delta_{3}^{k} x^{\alpha} x_{3}^{2 k}}{(2 k)!} .
$$

Theorem 23 The polynomials $S_{m}^{\alpha}, T_{m}^{\beta}$ and $F_{m}^{\gamma}$ are right linearly independent over $\mathcal{C} \ell_{3}$ for $\alpha \in \Lambda_{1}^{m}, \beta \in \Lambda_{2}^{m}$ and $\gamma \in \Lambda_{3}^{m}$ and therefore form a basis of the right $\mathrm{Cl}_{3}$-module generated by the homogeneous polynomial $H$-solutions of degree $m$.

Proof. By Prosition 21 it suffices to prove the linear independency over $\mathbb{H}$. To that end assume that

$$
\begin{equation*}
\sum_{\alpha \in \Lambda_{1}^{m}} S_{m}^{\alpha} a(\alpha)+\sum_{\beta \in \Lambda_{2}^{m}} T_{m}^{\beta} b(\beta)+\sum_{\gamma \in \Lambda_{3}^{m}} F_{m}^{\gamma} c(\gamma)=0 \tag{27}
\end{equation*}
$$

for some coefficients in $\mathbb{H}$. Differentiating (27) with respect to $x_{3}$ and evaluating at $x_{3}=0$ yield $\sum_{\alpha \in \Lambda_{1}^{m}} x^{\alpha} a(\alpha)=0$ and thus $\alpha(\alpha)=0$ for all $\alpha \in \Lambda_{1}^{m}$. Evaluating at $x_{3}=0$ yields $b(\gamma)=0$ for all $\gamma \in \Lambda_{3}^{m}$. Finally, since the polynomials $T_{m}^{\beta}$ with $\beta \in \Lambda_{2}^{m}$ are linearly independent we obtain $b(\beta)=0$ for all $\beta \in \Lambda_{2}^{m}$. We are considering

$$
\binom{m+1}{2}+\binom{m}{2}+\binom{m+1}{1}=\binom{m+2}{2}+\binom{m}{2}
$$

polynomials. Since by [3, Theorem 43] the dimension of the right $C l_{3}$-module generated by the homogeneous polynomial $H$-solutions of degree $m$ is

$$
\binom{m+2}{2}+\binom{m}{2}
$$

we have a basis.
Proposition 24 The polynomial $L_{m}^{\alpha}$ has a presentation

$$
L_{m}^{\alpha}=\sum_{\beta \in \Lambda_{1}^{m}} S_{m}^{\beta} a(\beta)+\sum_{\gamma \in \Lambda_{3}^{m}} F_{m}^{\gamma} b(\gamma),
$$

where $a(\beta) \in \mathbb{H}$ and $b(\gamma) \in \mathbb{H}$.
Proof. The polynomial $L_{m}^{\alpha}$ has a presentation in terms of the polynomials $S_{m}^{\delta}, T_{m}^{\beta}$ and $F_{m}^{\gamma}$ for $\delta \in \Lambda_{1}^{m}, \beta \in \Lambda_{2}^{m}$ and $\gamma \in \Lambda_{3}^{m}$ by Theorem 23. Since by Lemma $15 \frac{\partial^{2} Q L_{m}^{\alpha}}{\partial x_{3}^{2}}(\cdot, 0)=0$ and by Lemma $17 \frac{\partial^{2} Q T_{m}^{\beta}}{\partial x_{3}^{2}}(\cdot, 0)=2 x^{\beta} \neq 0$ the presentation does not contain polynomials $T_{m}^{\beta}$.

Proposition 25 Let $R_{m}$ be a homogenous polynomial $H$-solution of degree $m \in \mathbb{N}$. If

$$
\frac{\partial Q R_{m}}{\partial x_{3}}(\cdot, 0)=0 \text { and } \frac{\partial^{2} Q R_{m}}{\partial x_{3}^{2}}(\cdot, 0)=0
$$

then $R_{m}$ is a homogenous monogenic polynomial $H$-solution independent of $x_{3}$.

Proof. We can present $R_{m}$ in the basis $S_{m}^{\delta}, T_{m}^{\beta}$ and $F_{m}^{\gamma}$ for $\delta \in \Lambda_{1}^{m}, \beta \in$ $\Lambda_{2}^{m}$ and $\gamma \in \Lambda_{3}^{m}$. Since $\frac{\partial^{2} T_{m}^{\beta}}{\partial x_{3}^{2}}(\cdot, 0)=2 x^{\beta} \neq 0$ by Lemma 17 and $\frac{\partial S_{m}^{\alpha}}{\partial x_{3}}(\cdot, 0)=$ $x^{\alpha} \neq 0$ by Lemma 22 the presentation can contain only polynomials $F_{m}^{\gamma}$ and thus $R_{m}$ is a homogenous monogenic polynomial $H$-solution independent of $x_{3}$.

Theorem 26 Let $\alpha \in \Lambda_{1}^{m}, \beta \in \Lambda_{2}^{m}, \gamma \in \Lambda_{3}^{m}$ and $\delta \in \Lambda_{2}^{m+1}$. Then the polynomials $S_{m}^{\alpha}, T_{m}^{\beta}, F_{m}^{\gamma}$ and $\frac{\partial T_{m+1}^{\delta}}{\partial x_{3}}$ are right linearly independent over $\mathcal{C} \ell_{3}$ and form a basis for the right module of homogeneous holomorphic Cliffordian polynomials of degree $m$.

Proof. Suppose that

$$
\sum S^{\alpha} a(\alpha)+\sum T_{m}^{\beta} b(\beta)+\sum F^{\gamma} c(\gamma)+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} d(\delta)=0
$$

for some coefficients in $\mathcal{C} \ell_{3}$. Decomposing the coefficients yields

$$
\begin{array}{r}
0=\sum S^{\alpha} P a(\alpha)+\sum T_{m}^{\beta} P b(\beta)+\sum F^{\gamma} P c(\gamma) \\
+\sum S^{\alpha} Q a(\alpha) e_{3}+\sum T_{m}^{\beta} Q b(\beta) e_{3}+\sum F^{\gamma} Q c(\gamma) e_{3}+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} d(\delta), \tag{28}
\end{array}
$$

where $\sum S^{\alpha} P a(\alpha)+\sum T_{m}^{\beta} P b(\beta)+\sum F^{\gamma} P c(\gamma)$ is a hypermonogenic function. Hence

$$
\begin{array}{r}
h_{1}=\sum S^{\alpha} Q a(\alpha) e_{3}+\sum T_{m}^{\beta} Q b(\beta) e_{3}+\sum F^{\gamma} Q c(\gamma) e_{3}  \tag{29}\\
+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} Q d(\delta) e_{3}
\end{array}
$$

for some hypermonogenic function $h_{1}$. Since by Lemma 8 the function

$$
\sum \frac{\partial T_{m+1}^{\delta} Q d(\delta)}{\partial x_{3}} e_{3}+\sum \frac{2 Q\left(T_{m+1}^{\delta} Q d(\delta)\right)}{x_{3}}=h_{2}
$$

is hypermonogenic, the function

$$
\begin{array}{r}
h_{1}-h_{2}=\sum S^{\alpha} Q a(\alpha) e_{3}+\sum T_{m}^{\beta} Q b(\beta) e_{3}+\sum F^{\gamma} Q c(\gamma) e_{3} \\
+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)-\sum \frac{2 Q T_{m+1}^{\delta}}{x_{3}} Q^{\prime} d(\beta)
\end{array}
$$

is hypermonogenic. Applying (8) to

$$
\begin{array}{r}
Q\left(h_{1}-h_{2}\right)=\sum P S^{\alpha} Q a(\alpha)+\sum P T_{m}^{\beta} Q b(\beta) \\
+\sum P F^{\gamma} Q c(\gamma)+\sum \frac{\partial Q T_{m+1}^{\delta}}{\partial x_{3}} P^{\prime} d(\beta)
\end{array}
$$

we infer

$$
\begin{array}{r}
0=\sum P S^{\alpha}(\cdot, 0) Q a(\alpha)+\sum P T_{m}^{\beta}(\cdot, 0) Q b(\beta) \\
+\sum P F^{\gamma}(\cdot, 0) Q c(\gamma)+\sum \frac{\partial Q T_{m+1}^{\delta}}{\partial x_{3}}(\cdot, 0) P^{\prime} c(\beta) .
\end{array}
$$

Using (22) and (23) we obtain

$$
\sum P S^{\alpha}(\cdot, 0) Q a(\alpha)+\sum P F^{\gamma}(\cdot, 0) Q c(\gamma)=0
$$

and thus

$$
\begin{equation*}
\sum D_{2} P S^{\alpha}(\cdot, 0) Q a(\alpha)+\sum D_{2} P F^{\gamma}(\cdot, 0) Q c(\gamma)=0 \tag{30}
\end{equation*}
$$

For hypermonogenic functions $S^{\alpha}$ and $F^{\gamma}$ it holds by (9)

$$
\begin{equation*}
D_{2} P S^{\alpha}(\cdot, 0)=-\frac{\partial Q^{\prime} S^{\alpha}}{\partial x_{3}}(\cdot, 0) \tag{31}
\end{equation*}
$$

and

$$
\begin{equation*}
D_{2} P F^{\gamma}(\cdot, 0)=-\frac{\partial Q^{\prime} F^{\gamma}}{\partial x_{3}}(\cdot, 0)=0 \tag{32}
\end{equation*}
$$

where the last equality holds since $F^{\gamma}$ does not depend on $x_{3}$. Thus the equation (30) becomes

$$
\sum \frac{\partial Q^{\prime} S^{\alpha}}{\partial x_{3}}(\cdot, 0) Q a(\alpha)=\sum x^{\alpha} Q a(\alpha)=0
$$

and we obtain

$$
\begin{equation*}
Q a(\alpha)=0 \tag{33}
\end{equation*}
$$

for all $\alpha$. Substituting (33) to (28) we infer

$$
\begin{aligned}
0=\sum & S^{\alpha} P a(\alpha)+\sum T_{m}^{\beta} P b(\beta)+\sum T_{m}^{\beta} Q b(\beta) e_{3}+\sum F^{\gamma} P c(\gamma) \\
& +\sum F^{\gamma} Q c(\gamma) e_{3}+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} Q d(\delta) e_{3} .
\end{aligned}
$$

Separating the $P$-part we find out the equation

$$
\begin{aligned}
0=\sum P & S^{\alpha} P a(\alpha)+\sum P T_{m}^{\beta} P b(\beta)-\sum Q T_{m}^{\beta} Q^{\prime} b(\beta)+\sum P F^{\gamma} P c(\gamma) \\
& -\sum Q F^{\gamma} Q^{\prime} c(\gamma)+\sum \frac{\partial P T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)-\sum \frac{\partial Q T_{m+1}^{\delta}}{\partial x_{3}} Q^{\prime} d(\delta) .
\end{aligned}
$$

Hence we have

$$
\begin{align*}
0=\sum \frac{\partial P S^{\alpha}}{\partial x_{3}} & P a(\alpha)+\sum \frac{\partial P T_{m}^{\beta}}{\partial x_{3}} P b(\beta)-\sum \frac{\partial Q T_{m}^{\beta}}{\partial x_{3}} Q^{\prime} b(\beta)  \tag{34}\\
& +\sum \frac{\partial^{2} P T_{m+1}^{\delta}}{\partial x_{3}^{2}} P d(\delta)-\sum \frac{\partial^{2} Q T_{m+1}^{\delta}}{\partial x_{3}^{2}} Q^{\prime} d(\delta),
\end{align*}
$$

since $F^{\gamma}$ is independent of $x_{3}$. By (20) $P T_{k}^{\alpha}$ has only terms with odd powers of $x_{3}$ with degree at least 3 and therefore

$$
\begin{equation*}
\frac{\partial^{2} P T_{m+1}^{\delta}}{\partial x_{3}^{2}}(\cdot, 0)=0 \text { and } \frac{\partial P T_{m}^{\beta}}{\partial x_{3}}(\cdot, 0)=0 . \tag{35}
\end{equation*}
$$

Furthermore, by (10) and (22) we have

$$
\frac{\partial P S^{\alpha}}{\partial x_{3}}(\cdot, 0)=0 \text { and } \frac{\partial Q T_{m}^{\beta}}{\partial x_{3}}(\cdot, 0)=0
$$

The equation (34) evaluated at $x_{3}=0$ reduces to

$$
\sum \frac{\partial Q^{2} T_{m+1}^{\delta}}{\partial x_{3}^{2}}(\cdot, 0) Q^{\prime} d(\delta)=\sum 2 x^{\delta} Q^{\prime} d(\delta)=0
$$

and therefore

$$
Q d(\delta)=0
$$

for all $\delta$.
Separating the $Q$-part in (28) and setting $Q d(\delta)=0$ we obtain

$$
\begin{gathered}
0=\sum Q S^{\alpha} P^{\prime} a(\alpha)+\sum Q T_{m}^{\beta} P^{\prime} b(\beta)+\sum Q F^{\gamma} P^{\prime} c(\gamma) \\
+\sum P T_{m}^{\beta} Q b(\beta)+\sum P F^{\gamma} Q c(\gamma)+\sum \frac{\partial Q T_{m+1}^{\delta}}{\partial x_{3}} P^{\prime} d(\delta) .
\end{gathered}
$$

Differentiating twice with respect to the variable $x_{3}$ and evaluating at $x_{3}=0$ we infer using Lemma 15, (35) and (22)

$$
\begin{array}{r}
0=\sum \frac{\partial^{2} Q S^{\alpha}}{\partial x_{3}^{2}}(\cdot, 0) P^{\prime} a(\alpha)+\sum \frac{\partial^{2} Q T_{m}^{\beta}}{\partial x_{3}^{2}}(\cdot, 0) P^{\prime} b(\beta) \\
+\sum \frac{\partial^{2} P T_{m}^{\beta}}{\partial x_{3}^{2}}(\cdot, 0) Q b(\beta)+\sum \frac{\partial^{3} Q T_{m+1}^{\delta}}{\partial x_{3}^{3}}(\cdot, 0) P^{\prime} d(\delta) \\
\quad=\sum \frac{\partial^{2} Q T_{m}^{\beta}}{\partial x_{3}^{2}}(\cdot, 0) P^{\prime} b(\beta)=\sum 2 x^{\alpha} P^{\prime} b(\beta) .
\end{array}
$$

Thus $\operatorname{Pb}(\beta)=0$ for all $\beta$.
Collecting all the previous information to (28) we have

$$
\begin{align*}
0=\sum S^{\alpha} P a & (\alpha)+\sum F^{\gamma} P c(\gamma)+\sum T_{m}^{\beta} Q b(\beta) e_{3}  \tag{36}\\
& +\sum F^{\gamma} Q c(\gamma) e_{3}+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)
\end{align*}
$$

This means that the function

$$
\begin{array}{r}
h=-\sum S^{\alpha} P a(\alpha)-\sum F^{\gamma} P c(\gamma) \\
=\sum T_{m}^{\beta} Q b(\beta) e_{3}+\sum F^{\gamma} Q c(\gamma) e_{3}+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)
\end{array}
$$

is hypermonogenic and the function

$$
P h=-\sum Q T_{m}^{\beta} Q^{\prime} b(\beta)-\sum Q F^{\gamma} Q^{\prime} c(\gamma)+\sum \frac{\partial P T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)
$$

is hyperbolic harmonic. Since $Q T_{m}^{\beta}, Q F^{\gamma}$ and $\frac{\partial P T_{m+1}^{\delta}}{\partial x_{3}}$ are eigenfunctions of the Laplace-Beltrami operator, applying $x_{3}^{2} \triangle_{H} P h=0$ we obtain

$$
\begin{array}{r}
0=-\sum x_{3}^{2} \triangle_{H}\left(Q T_{m}^{\beta}\right) Q^{\prime} b(\beta)-\sum x_{3}^{2} \triangle_{H}\left(Q F^{\gamma}\right) Q^{\prime} c(\gamma) \\
+\sum x_{3}^{2} \triangle_{H}\left(\frac{\partial P T_{m+1}^{\delta}}{\partial x_{3}}\right) P d(\delta) \\
=-\sum-2 Q T_{m}^{\beta} Q b(\beta) e_{3}-\sum-2 Q F^{\gamma} Q^{\prime} c(\gamma)+\sum-2 \frac{\partial P T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta) \\
=-2 P h .
\end{array}
$$

Hence $P h=0$, which by (9) implies

$$
-\frac{\partial Q^{\prime} h}{\partial x_{3}}(\cdot, 0)=\sum D_{2} P h(\cdot, 0)=0 .
$$

On the other hand

$$
\begin{array}{r}
-\frac{\partial Q^{\prime} h}{\partial x_{3}}(\cdot, 0)=\sum \frac{\partial Q S^{\alpha}}{\partial x_{3}}(\cdot, 0) P a(\alpha)+\sum \frac{\partial Q F^{\gamma}}{\partial x_{3}}(\cdot, 0) P c(\gamma) \\
=\sum \frac{\partial Q S^{\alpha}}{\partial x_{3}}(\cdot, 0) P a(\alpha)=\sum x^{\alpha} P a(\alpha)=0
\end{array}
$$

and we deduce

$$
\begin{equation*}
P a(\alpha)=0 . \tag{37}
\end{equation*}
$$

After (37) the sum (36) reduces to

$$
\begin{equation*}
\sum F^{\gamma} P c(\gamma)+\sum T_{m}^{\beta} Q b(\beta) e_{3}+\sum F^{\gamma} Q c(\gamma) e_{3}+\sum \frac{\partial T_{m+1}^{\delta}}{\partial x_{3}} P d(\delta)=0 \tag{38}
\end{equation*}
$$

Differentiating (38) with respect to the variable $x_{3}$ and evaluating at $x_{3}=0$ we infer

$$
\begin{array}{r}
0=\sum \frac{\partial P T_{m}^{\beta}}{\partial x_{3}}(\cdot, 0) Q b(\beta) e_{3}-\sum \frac{\partial Q T_{m}^{\beta}}{\partial x_{3}}(\cdot, 0) Q^{\prime} b(\beta) \\
+\sum \frac{\partial^{2} P T_{m+1}^{\delta}}{\partial x_{3}^{2}}(\cdot, 0) P d(\delta)-\sum \frac{\partial^{2} Q T_{m+1}^{\delta}}{\partial x_{3}^{2}}(\cdot, 0) P^{\prime} d(\delta) \\
\quad=-\sum \frac{\partial^{2} Q T_{m+1}^{\delta}}{\partial x_{3}^{2}}(\cdot, 0) P^{\prime} d(\delta)=-\sum 2 x^{\delta} P^{\prime} d(\delta),
\end{array}
$$

and $\operatorname{Pd}(\delta)=0$ for all $\delta$. Since the polynomials $F^{\gamma}$ are linearly independent over $\mathcal{C} \ell_{3}$ and do not depend on $x_{3}$ when $\gamma \in \Lambda_{3}^{m}$ evaluating at $x_{3}=0$ we infer $c(\gamma)=0$ for all $\gamma \in \Lambda_{3}^{m}$. Since the polynomials $T_{m}^{\beta}$ are linearly independent over $\mathcal{C} \ell_{3}$, the only coefficients remaining in (38) must vanish and therefore $Q b(\beta)=0$ for all $\beta$. The number of polynomials

$$
\binom{m+2}{2}+\binom{m}{2}+\binom{m+1}{2}
$$

is the same as the dimension in 26 completing the proof.
Our main result, Theorem 26, can be written in an equivalent form using Theorem 24.

Theorem 27 Let $\alpha \in \Lambda_{0}^{m}, \beta \in \Lambda_{2}^{m}$, and $\gamma \in \Lambda_{2}^{m+1}$. The polynomials $L_{m}^{\alpha}, T_{m}^{\beta}$ and $\frac{\partial T_{m+1}^{\gamma}}{\partial x_{3}}$ are right linearly independent over $\mathcal{C} \ell_{3}$ and form a basis for the right module of homogeneous holomorphic Cliffordian polynomials of degree $m$.

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