# A NOTE ON THE CLIFFORD FOURIER-STIELTJES TRANSFORM AND ITS PROPERTIES 

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#### Abstract

The purpose of this article is to provide an overview of the real Clifford FourierStieltjes transform (CFST) and of its important properties. Additionally, we introduce the definition of convolution of Clifford functions of bounded variation.


## 1 INTRODUCTION

### 1.1 Function of bounded variation and its Fourier-Stieltjes transform

The concept of functions of bounded variation plays an important role in probability theory. Among the known attempts made in this direction, the most notable ones are due to Beurling [1], Bochner [2, 6], and Cramér [10].

Let $\sigma(x)$ be a nondecreasing real or complex-valued function of the real variable $x$, having bounded variation on the whole real axis: $\int_{\mathbb{R}}|d \sigma(x)|<\infty$. It is well known that $\sigma(x)$ has at most an enumerable set of discontinuity points. In such a point we define

$$
\sigma(x)=\frac{1}{2}[\sigma(x+0)+\sigma(x-0)] .
$$

For any function $\sigma(x)$ as above, the expression

$$
\begin{equation*}
f(t)=\int_{\mathbb{R}} e^{i t x} d \sigma(x), \quad-\infty<t<\infty \tag{1}
\end{equation*}
$$

defines the Fourier-Stieltjes transform of $\sigma(x)$. The Fourier-Stieltjes transform (FST) is a wellknown generalization of the classical Fourier transform, and is frequently applied in certain areas of theoretical and applied probability and stochastic processes contexts.

There has recently been much interest in the construction of higher dimensional counterparts of the Fourier-Stieltjes transform in the framework of quaternion and Clifford analyses [13, 14]. It is the object of the present paper to give an overview on the (real) Clifford Fourier-Stieltjes transform (CFST), and on some of its important properties [13]. The underlying functions are continuous functions of bounded variation defined in $\mathbb{R}^{m}$ and taking values in a Clifford algebra. We also introduce the definition of convolution of Clifford functions of bounded variation. The convolution is related to pairs of functions belonging to a certain class in the same way as in the classical case.

The used methods also allow a generalization to the case of Clifford functions that satisfy higher dimensional generalizations of Cauchy-Riemann or Dirac systems. We leave the details of this slight generalization to the interested reader.

### 1.2 Some basic concepts of Clifford analysis

In the present subsection, we review some definitions and basic algebraic facts of a special Clifford algebra of signature $(0, m)$. For more details, we refer the reader to [7, 16].

Let $\left\{e_{1}, e_{2}, \ldots, e_{m}\right\}$ be an orthonormal basis of the Euclidean vector space $\mathbb{R}^{m}$ with a product according to the multiplication rules:

$$
e_{i} e_{j}+e_{j} e_{i}=-2 \delta_{i, j}, \quad i, j=1, \ldots, m
$$

where $\delta_{i, j}$ is the Kronecker symbol. Whence, the set $\left\{e_{A}: A \subseteq\{1, \ldots, m\}\right\}$ with $e_{A}=$ $e_{h_{1}} e_{h_{2}} \ldots e_{h_{r}}, 1 \leq h_{1}<\ldots<h_{r} \leq m$, and $e_{\phi}=1$ forms a basis of the $2^{m}$-dimensional Clifford algebra $C l_{0, m}$ over $\mathbb{R}$. Any Clifford number $a$ in $C l_{0, m}$ may thus be written as $a=\sum_{A} e_{A} a_{A}$, $a_{A} \in \mathbb{R}$, or still as $a=\sum_{k=0}^{m}[a]_{k}$, where $[a]_{k}=\sum_{|A|=k} e_{A} a_{A}$ is the so-called $k$-vector part of $a(k=0,1, \ldots, m)$. The real vector space $\mathbb{R}^{m}$ will be embedded in $C l_{0, m}$ by identifying the element $\left(x_{1}, \ldots, x_{m}\right) \in \mathbb{R}^{m}$ with the Clifford vector $\mathbf{x}$ given by

$$
\mathbf{x}:=e_{1} x_{1}+\cdots+e_{m} x_{m}
$$

It is worth noting that the square of a vector x is scalar-valued and equals the norm squared up to a minus sign: $\mathbf{x}^{2}=-|\mathbf{x}|^{2}$. Throughout the paper, we consider $C l_{0, m}$-valued functions defined in $\mathbb{R}^{m}$, i.e. functions of the form

$$
\begin{equation*}
f: \mathbb{R}^{m} \longrightarrow C l_{0, m}, \quad f(\mathbf{x})=\sum_{A} f_{A}(\mathbf{x}) e_{A} \tag{2}
\end{equation*}
$$

where $f_{A}$ are real-valued functions defined in $\mathbb{R}^{m}$. Properties (like integrability, continuity or differentiability) that are ascribed to $f$ have to be fulfilled by all components $f_{A}$.

Let

$$
L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right):=\left\{f \in \mathbb{R}^{m} \longrightarrow C l_{0, m}: \int_{\mathbb{R}^{m}}|f(\mathbf{x})| d \sigma(\mathbf{x})<\infty\right\}
$$

denote the linear Hilbert space of integrable $C l_{0, m}$-valued functions defined in $\mathbb{R}^{m}$. The leftsided Clifford Fourier transform (CFT) of $f \in L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)$ is given by [9]

$$
\begin{equation*}
\mathcal{F}(f): \mathbb{R}^{m} \longrightarrow C l_{0, m}, \quad \mathcal{F}(f)(\boldsymbol{\omega}):=\int_{\mathbb{R}^{m}} \mathbf{e}(\boldsymbol{\omega}, \mathbf{x}) f(\mathbf{x}) d \sigma(\mathbf{x}), \tag{3}
\end{equation*}
$$

where the kernel function

$$
\mathbf{e}: \mathbb{R}^{m} \times \mathbb{R}^{m} \longrightarrow C l_{0, m}, \quad \mathbf{e}(\boldsymbol{\omega}, \mathbf{x}):=\prod_{i=1}^{m} e^{-e_{m+1-i} \omega_{m+1-i} x_{m+1-i}}
$$

For $i=1, \ldots, m, x_{i}$ will denote the space and $\omega_{i}$ the angular frequency variables. It is of interest to remark at this point that the product in (3) has to be performed in a fixed order since, in general, $\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})$ does not commute with every element of $C l_{0, m}$.

Under suitable conditions, the original signal $f$ can be reconstructed from $\mathcal{F}(f)$ by the inverse transform. The inverse (left-sided) Clifford Fourier transform of $g \in L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)$ is defined as follows:

$$
\begin{equation*}
\mathcal{F}^{-1}(g): \mathbb{R}^{m} \longrightarrow C l_{0, m}, \quad \mathcal{F}^{-1}(g)(\mathbf{x})=\frac{1}{(2 \pi)^{m}} \int_{\mathbb{R}^{m}} \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})} g(\boldsymbol{\omega}) d \sigma(\boldsymbol{\omega}) \tag{4}
\end{equation*}
$$

where $\overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}:=\prod_{i=1}^{m} e^{e_{i} \omega_{i} x_{i}}$ is called the inverse (left-sided) Clifford Fourier kernel.

## 2 THE CLIFFORD FOURIER-STIELTJES TRANSFORM AND ITS PROPERTIES

In this section we review the (real) Clifford Fourier-Stieltjes transform (CFST).

### 2.1 The (real) Clifford Fourier-Stieltjes transform

In the sequel, consider the function

$$
\alpha: \mathbb{R}^{m} \longrightarrow C l_{0, m}, \quad \mathbf{x} \longmapsto \alpha(\mathbf{x}):=\prod_{i=1}^{m} \alpha^{i}\left(x_{i}\right)
$$

where $\alpha^{i}: \mathbb{R} \longrightarrow C l_{0, m}$ are of bounded variation on $\mathbb{R}$ :

$$
\int_{\mathbb{R}}\left|d \alpha^{i}\left(x_{i}\right)\right|:=M_{i}<\infty
$$

and such that $\left|\alpha^{i}\right| \leq \delta_{i}$ for real numbers $\delta_{i}<\infty$. From here it follows that $\alpha$ is of bounded variation also, since it holds

$$
\int_{\mathbb{R}^{m}}|d \alpha(\mathbf{x})|=\int_{\mathbb{R}^{m}} \prod_{i=1}^{m}\left|d \alpha^{i}\left(x_{i}\right)\right|=\prod_{i=1}^{m} M_{i}:=M<\infty
$$

and, such that

$$
|\alpha(\mathbf{x})| \leq \prod_{i=1}^{m} \delta_{i}:=\delta<\infty
$$

The class of all such functions is denoted by $(V)$. Unless otherwise stated, throughout this paper the product is meant to be performed in a fixed order:

$$
\prod_{i=1}^{m} \alpha^{i}\left(x_{i}\right):=\alpha^{1}\left(x_{1}\right) \alpha^{2}\left(x_{2}\right) \ldots \alpha^{m}\left(x_{m}\right)
$$

For the sets of discontinuity points of each $\alpha^{i}\left(x_{i}\right)$, we further assume that there exist the limits

$$
\lim _{x_{i} \longrightarrow y_{i}+} \alpha^{i}\left(x_{i}\right)=\alpha^{i}\left(y_{i}+0\right), \quad \text { and } \quad \lim _{x_{i} \longrightarrow y_{i}-} \alpha^{i}\left(x_{i}\right)=\alpha^{i}\left(y_{i}-0\right) \quad(i=1, \ldots, m)
$$

(taken over all directions) for which

$$
\alpha^{i}\left(y_{i}\right)=\frac{1}{2}\left[\alpha^{i}\left(y_{i}+0\right)+\alpha^{i}\left(y_{i}-0\right)\right]
$$

holds almost everywhere on $\mathbb{R}$. Each function $\alpha^{i}$ is said to be a Clifford distribution.
The idea behind the construction of a Clifford counterpart of the Stieltjes integral is to replace the exponential function in (1) by a suitable (noncommutative) exponential product. Due to the noncommutativity of the algebra, we recall two different types of CFST [13]:

Definition 2.1. The CFST $\mathcal{F} \mathcal{S}(\alpha): \mathbb{R}^{m} \longrightarrow C l_{0, m}$ of $\alpha(\mathbf{x})$ is defined as the Stieltjes integrals:

1. Right-sided CFST:

$$
\begin{equation*}
\mathcal{F} \mathcal{S}_{r}(\alpha)(\boldsymbol{\omega}):=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})} \tag{5}
\end{equation*}
$$

2. Left-sided CFST:

$$
\begin{equation*}
\mathcal{F} \mathcal{S}_{l}(\alpha)(\boldsymbol{\omega}):=\int_{\mathbb{R}^{m}} \mathbf{e}(\boldsymbol{\omega},-\mathbf{x}) d \alpha(\mathbf{x}) \tag{6}
\end{equation*}
$$

The function $\alpha(\mathrm{x})$ which generates (5) and (6) is essentially unique.
Remark 2.2. We recall the reader that, the order of the exponentials in (5)-(6) are fixed because of the noncommutativity of the underlying product. It is of interest to remark at this point that in the case $m=2$ the formulae above reduce to the definitions for the right- and left-sided QFST introduced by the authors in [14]. Detailed information about the QFST and its properties can be found in [14]. For $m=1$ the CFST is identical to the classical FST.

Remark 2.3. Throughout this text we may investigate the integral (5) only that, for simplicity, we denote by $\mathcal{F S}(\alpha)$. Nevertheless, all computations can be easily converted for (6). In view of (5) and (6), a straightforward calculation shows that:

$$
\mathcal{F} \mathcal{S}(\alpha)(\boldsymbol{\omega})=\overline{\int_{\mathbb{R}^{m}} \mathbf{e}(\boldsymbol{\omega}, \mathbf{x}) \overline{d \alpha(\mathbf{x})}}=\overline{\mathcal{F} \mathcal{S}_{l}(\bar{\alpha})(-\boldsymbol{\omega})}
$$

From now on, we denote the class of functions which can be represented as (5) by $\mathcal{B}$. Functions in $\mathcal{B}$ are called (right) Clifford Bochner functions and $\mathcal{B}$ will be referred to as the (right) Clifford Bochner set. It follows that members of $\mathcal{B}$ are entire functions of the real variables $\omega_{i}$.

It is immediately clear that $\mathcal{B}$ is a linear space, and every element $f$ of $\mathcal{B}$ is a bounded uniformly continuous function:

$$
\begin{equation*}
|f(\boldsymbol{\omega})| \leq \int_{\mathbb{R}^{m}}|d \alpha(\mathbf{x})|=M<\infty \tag{7}
\end{equation*}
$$

We recall from [13] the following result.
Theorem 2.4. If a function belongs to $\mathcal{B}$ and is identically equal to zero for all $\omega_{i} \leq 0$ ( $i=$ $1, \ldots, m$ ), then it is the Fourier-Stieltjes transform of an absolutely continuous function.

Proof. Let $f$ be any function in $\mathcal{B}$. By hypothesis,

$$
\begin{equation*}
f(\boldsymbol{\omega})=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}, \tag{8}
\end{equation*}
$$

where $\int_{\mathbb{R}^{m}}|d \sigma(\mathbf{x})|=M<\infty$. For $\mathbf{x}=x_{1} e_{1}+\cdots+x_{m} e_{m} \in C l_{0, m}$ we set

$$
C l_{0, m} \ni \tilde{\mathbf{x}}:=\frac{1}{2} \sum_{i=1}^{m}\left(x_{i}^{2}+1\right) e_{i} .
$$

Let $\mathbb{R}_{0}^{m,+}:=\underbrace{\mathbb{R}_{0}^{+} \times \cdots \times \mathbb{R}_{0}^{+}}_{m \text { times }}$. We define the function $G(\mathbf{x})$ as follows

$$
G(\mathbf{x}):=\frac{1}{(2 \pi)^{m}} \int_{\mathbb{R}_{0}^{m,+}} f(\boldsymbol{\omega}) \overline{\mathbf{e}(\boldsymbol{\omega}, \tilde{\mathbf{x}})} d \boldsymbol{\omega}
$$

Evidently $G(\mathbf{x})$ is analytic for all $x_{i}(i=1, \ldots, m)$ since it is the product of analytic functions for any fixed $x_{i}$. We suppose from now on that this condition is satisfied. From the definition of the function $f$ follows that there exists a constant $M>0$ so that $|f(\boldsymbol{\omega})| \leq M<\infty$. From (8) and since $f(\boldsymbol{\omega})=0$ for all $\omega_{i} \leq 0(i=1, \ldots, m)$, we may write

$$
|G(\mathbf{x})| \leq \frac{1}{(2 \pi)^{m}} \int_{\mathbb{R}_{0}^{m,+}}|f(\boldsymbol{\omega})| \prod_{i=1}^{m} e^{-\frac{x_{i}^{2}+1}{2} \omega_{i}} d \omega_{i} \leq \frac{M}{(2 \pi)^{m}} \prod_{i=1}^{m} \frac{2}{x_{i}^{2}+1}
$$

By straightforward calculation we may show that

$$
\int_{\mathbb{R}^{m}}|G(\mathbf{x})| d \mathbf{x} \leq \frac{M}{(2 \pi)^{m}} \prod_{i=1}^{m} \int_{\mathbb{R}} \frac{2}{x_{i}^{2}+1} d x_{i}=M<\infty
$$

This proves the theorem.

For practical purposes, if $f \in \mathcal{B}$ is given then for any real variables $\omega_{i}$, and real constants $a_{i}$ $(i=1, \ldots, m)$ a direct computation shows that

$$
\begin{aligned}
|f(\boldsymbol{\omega})| & =\left|\left(\int_{-\infty}^{a_{1}}+\int_{a_{1}}^{\infty}\right)\left(\int_{-\infty}^{a_{2}}+\int_{a_{2}}^{\infty}\right) \ldots\left(\int_{-\infty}^{a_{m}}+\int_{a_{m}}^{\infty}\right) d \alpha(\mathbf{x}) \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}\right| \\
& \leq \prod_{i=1}^{m}\left(\left|\alpha^{i}(\infty)-\alpha^{i}\left(a_{m+1-i}\right)\right|+\left|\alpha^{i}\left(a_{m+1-i}\right)-\alpha^{i}(-\infty)\right|\right)
\end{aligned}
$$

since $|\overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}|=1$. If $f \in \mathcal{B}$ is given, then

$$
f(\mathbf{0})=\prod_{i=1}^{m}\left(\alpha^{i}(\infty)-\alpha^{i}(-\infty)\right)
$$

In particular, a simple argument gives

$$
\begin{equation*}
f(-\boldsymbol{\omega})=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \overline{\mathbf{e}(-\boldsymbol{\omega}, \mathbf{x})}=\overline{\int_{\mathbb{R}^{m}} \mathbf{e}(-\boldsymbol{\omega}, \mathbf{x}) \overline{d \alpha(\mathbf{x})}}=\overline{g(\boldsymbol{\omega})}, \tag{9}
\end{equation*}
$$

where $g$ is any function which can be represented as $\overline{\mathcal{F} \mathcal{S}_{l}(\bar{\alpha})}(\boldsymbol{\omega})$.

### 2.2 Lévy's inversion formula

This subsection provides an explicit formula for computing a Clifford function once its Fourier-Stieltjes integral is known.

Theorem 2.5. For every $\alpha^{i}: \mathbb{R} \longrightarrow C l_{0, m}(i=1, \ldots, m)$, we consider the functions

$$
g_{i}\left(\omega_{i}\right)=\int_{\mathbb{R}} d \alpha^{i}\left(x_{i}\right) e^{e_{i} \omega_{i} x_{i}} .
$$

For any real numbers $a$ and $b$ the following equality holds:

$$
\begin{equation*}
\alpha^{i}(a)-\alpha^{i}(b)=\lim _{T \longrightarrow \infty} \frac{1}{2 \pi} \int_{-T}^{T} g_{i}\left(\omega_{i}\right) \frac{e^{e_{i} b \omega_{i}}-e^{e_{i} a \omega_{i}}}{e_{i} \omega_{i}} d \omega_{i} . \tag{10}
\end{equation*}
$$

In particular, it holds

$$
\alpha^{i}\left(x_{i}+0\right)-\alpha^{i}\left(x_{i}-0\right)=\lim _{T \longrightarrow \infty} \frac{1}{2 T} \int_{-T}^{T} g_{i}\left(\omega_{i}\right) e^{-e_{i} x_{i} \omega_{i}} d \omega_{i} .
$$

Proof. We begin with the following observation:

$$
\begin{aligned}
g_{i}\left(\omega_{i}\right)\left(e^{-e_{i} a \omega_{i}}-e^{-e_{i} b \omega_{i}}\right) & =\int_{\mathbb{R}} d \alpha^{i}\left(x_{i}\right) e^{e_{i} \omega_{i}\left(x_{i}-a\right)}-\int_{\mathbb{R}} d \alpha^{i}\left(x_{i}\right) e^{e_{i} \omega_{i}\left(x_{i}-b\right)} \\
& =\int_{\mathbb{R}} d \alpha^{i}\left(x_{i}+a\right) e^{e_{i} \omega_{i} x_{i}}-\int_{\mathbb{R}} d \alpha^{i}\left(x_{i}+b\right) e^{e_{i} \omega_{i} x_{i}}
\end{aligned}
$$

$$
\begin{gathered}
=\lim _{T \longrightarrow \infty}\left[\alpha^{i}(T+a) e^{e_{i} T \omega_{i}}-\alpha^{i}(-T+a) e^{-e_{i} T \omega_{i}}\right. \\
-\alpha^{i}(T+b) e^{e_{i} T \omega_{i}}+\sigma^{i}(-T+b) e^{-e_{i} T \omega_{i}} \\
\left.-\int_{-T}^{T}\left(\alpha^{i}\left(x_{i}+a\right)-\alpha^{i}\left(x_{i}+b\right)\right) d x_{i} e^{e_{i} \omega_{i} x_{i}} e_{i} \omega_{i}\right] \\
=-\int_{\mathbb{R}}\left(\alpha^{i}\left(x_{i}+a\right)-\alpha^{i}\left(x_{i}+b\right)\right) d x_{i} e^{e_{i} \omega_{i} x_{i}} e_{i} \omega_{i}
\end{gathered}
$$

Therefore, it is easy to see that

$$
g_{i}\left(\omega_{i}\right)\left(e^{-e_{i} a \omega_{i}}-e^{-e_{i} b \omega_{i}}\right) \frac{1}{-e_{i} \omega_{i}}=\int_{\mathbb{R}}\left(\alpha^{i}\left(x_{i}+a\right)-\alpha^{i}\left(x_{i}+b\right)\right) d x_{i} e^{e_{i} \omega_{i} x_{i}}
$$

From the last equality and from the inverse Fourier transform formula we find

$$
\alpha^{i}\left(x_{i}+a\right)-\alpha^{i}\left(x_{i}+b\right)=\frac{1}{2 \pi} \int_{\mathbb{R}} g_{i}\left(\omega_{i}\right) \frac{e^{-e_{i} a \omega_{i}}-e^{-e_{i} b \omega_{i}}}{-e_{i} \omega_{i}} e^{-e_{i} x_{i} \omega_{i}} d \omega_{i},
$$

and, in particular taking $x_{i}=0$ we find

$$
\alpha^{i}(a)-\alpha^{i}(b)=\frac{1}{2 \pi} \int_{\mathbb{R}} g\left(\omega_{i}\right) \frac{e^{-e_{i} a \omega_{i}}-e^{-e_{i} b \omega_{i}}}{-e_{i} \omega_{i}} d \omega_{i},
$$

and this completes the proof.
Formula (10) is known as the Lévy's inversion formula. It is immediately clear if two Clifford functions have the same Fourier-Stieltjes integral, then they are identical up to an additive (Clifford) constant.

## 3 UNIFORM CONTINUITY

In this section we discuss uniform continuity and its relationship to CFST. We begin by defining uniform continuity.

Definition 3.1. A Clifford function $f: \mathbb{R}^{m} \longrightarrow C l_{0, m}$ is uniformly continuous on $\mathbb{R}^{m}$ if and only if for all $\epsilon>0$ there exists a $\delta>0$ such that $|f(\boldsymbol{\omega})-f(\mathbf{t})|<\epsilon$ for all $\boldsymbol{\omega}, \mathbf{t} \in \mathbb{R}^{m}$ whenever $|\boldsymbol{\omega}-\mathbf{t}|<\delta$.

We now prove some results related to the asymptotic behaviour of the CFST which run:
Proposition 3.2. Let $f$ be an element of $\mathcal{B}$. For any natural number $n$, let $f^{n}: \mathbb{R}^{m-1} \times$ $[-n, n] \longrightarrow C l_{0, m}$ be the function given by

$$
f^{n}(\boldsymbol{\omega})=\int_{-n}^{n} \int_{\mathbb{R}^{m-1}} d \alpha(\mathbf{x}) \overline{\boldsymbol{e}(\boldsymbol{\omega}, \mathbf{x})}
$$

Then $f^{n}(\boldsymbol{\omega}) \longrightarrow_{n \longrightarrow \infty} f(\boldsymbol{\omega})$ uniformly. Also, if $f^{n}$ are uniformly continuous functions then $f$ is a uniformly continuous function.

Proof. A first straightforward computation shows that

$$
\begin{aligned}
\left|f(\boldsymbol{\omega})-f^{n}(\boldsymbol{\omega})\right| & =\left|\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}-\int_{-n}^{n} \int_{\mathbb{R}^{m-1}} d \alpha(\mathbf{x}) \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}\right| \\
& =\left|\int_{-\infty}^{-n} \int_{\mathbb{R}^{m-1}} d \alpha(\mathbf{x}) \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}+\int_{n}^{\infty} \int_{\mathbb{R}^{m-1}} d \alpha(\mathbf{x}) \overline{\mathbf{e}(\boldsymbol{\omega}, \mathbf{x})}\right| \\
& \leq \prod_{i=1}^{m-1}\left|\alpha^{i}(\infty)-\alpha^{i}(-\infty)\right|\left|\alpha^{m}(-n)-\alpha^{m}(-\infty)\right| \\
& +\prod_{i=1}^{m-1}\left|\alpha^{i}(\infty)-\alpha^{i}(-\infty)\right|\left|\alpha^{m}(\infty)-\alpha^{m}(n)\right|
\end{aligned}
$$

Moreover, having in mind that

$$
\alpha^{m}(-n)-\alpha^{m}(-\infty) \longrightarrow_{n \rightarrow \infty} 0, \quad \text { and } \quad \alpha^{m}(\infty)-\alpha^{m}(n) \longrightarrow_{n \rightarrow \infty} 0,
$$

and hence, $f^{n}(\boldsymbol{\omega}) \longrightarrow_{n \longrightarrow \infty} f(\boldsymbol{\omega})$ uniformly. In addition, we claim that if $f^{n}(\boldsymbol{\omega})$ are uniformly continuous functions it follows that $f(\boldsymbol{\omega})$ is an uniformly continuous function.

In like manner, we have an analogous result.
Proposition 3.3. Let $f$ be an element of $\mathcal{B}$. For any natural number n, let $f^{n}:[-n, n] \times$ $\mathbb{R}^{m-1} \longrightarrow C l_{0, m}$ be the function given by

$$
f^{n}(\boldsymbol{\omega})=\int_{\mathbb{R}^{m-1}} \int_{-n}^{n} d \alpha(\mathbf{x}) \overline{\boldsymbol{e}(\boldsymbol{\omega}, \mathbf{x})}
$$

Then $f^{n}(\boldsymbol{\omega}) \longrightarrow_{n \rightarrow \infty} f(\boldsymbol{\omega})$ uniformly. Also, if $f^{n}$ are uniformly continuous functions then $f$ is a uniformly continuous function.

Proposition 3.4. Let $f$ be an element of $\mathcal{B}$. For any natural number $n$, let $f^{n}:[-n, n]^{m} \longrightarrow$ $C l_{0, m}$ be the function given by

$$
f^{n}(\boldsymbol{\omega})=\int_{[-n, n]^{m}} d \alpha(\mathbf{x}) \overline{\boldsymbol{e}(\boldsymbol{\omega}, \mathbf{x})}
$$

Then $f^{n}(\boldsymbol{\omega}) \longrightarrow_{n \longrightarrow \infty} f(\boldsymbol{\omega})$ uniformly. Also, if $f^{n}$ are uniformly continuous functions then $f$ is a uniformly continuous function.
Proof. For simplicity and without loss of generality we will prove the case $m=2$ only. We set

$$
A:=d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) e^{e_{1} \omega_{1} x_{1}} e^{e_{2} \omega_{2} x_{2}}
$$

The key to the proof is the simple observation that:

$$
\begin{aligned}
\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} A-\int_{-n}^{n} \int_{-n}^{n} A & =\int_{-\infty}^{-n} \int_{-\infty}^{-n} A+\int_{-\infty}^{-n} \int_{-n}^{n} A+\int_{-\infty}^{-n} \int_{n}^{\infty} A \\
& +\int_{-n}^{n} \int_{-\infty}^{-n} A+\int_{-n}^{n} \int_{n}^{\infty} A \\
& +\int_{n}^{\infty} \int_{-\infty}^{-n} A+\int_{n}^{\infty} \int_{-n}^{n} A+\int_{n}^{\infty} \int_{n}^{\infty} A
\end{aligned}
$$

For the remaining part of the proof, we use similar arguments as in Proposition 3.2.

We come now to the main result of this section.
Theorem 3.5. Let $f \in \mathcal{B}$ be given, and $g: \mathbb{R}^{m} \longrightarrow C l_{0, m}$ be a continuous and absolutely integrable function. For any $\alpha: \mathbb{R}^{m} \longrightarrow C l_{0, m}$ the following relations hold:

1. $\int_{\mathbb{R}^{m}} f(\mathbf{t}) g(\boldsymbol{\omega}-\mathbf{t}) d \mathbf{t}=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \int_{\mathbb{R}^{m}} \overline{\boldsymbol{e}(\boldsymbol{\omega}, \mathbf{x})} g(\boldsymbol{\omega}-\mathbf{t}) d \mathbf{t}$;
2. $\int_{\mathbb{R}^{m}} f(\mathbf{t}) g(\mathbf{t}) d \mathbf{t}=(2 \pi)^{m} \int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \mathcal{F}^{-1}(g)(\mathbf{x})$.

Proof. Assume $g: \mathbb{R}^{m} \longrightarrow C l_{0, m}$ to be a continuous and absolutely integrable function. For any real variables $\rho_{i}(i=1, \ldots, m)$ let $\Omega_{\rho_{i}}:=\left[-\rho_{1}, \rho_{1}\right] \times \cdots \times\left[-\rho_{m}, \rho_{m}\right] \subset \mathbb{R}^{m}$. We now define the function

$$
R: \mathbb{R}^{m} \times \mathbb{R}^{m} \longrightarrow C l_{0, m}, \quad(\mathbf{x}, \boldsymbol{\rho}) \longmapsto R(\mathbf{x}, \boldsymbol{\rho}):=\int_{\Omega_{\rho_{i}}} \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}} g(\mathbf{t}) d \mathbf{t}
$$

Take

$$
f^{n}(\mathbf{t})=\int_{[-n, n]^{m}} d \alpha(\mathbf{x}) \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}}
$$

Using the fact that $g$ is an absolutely integrable function it follows

$$
\begin{align*}
\int_{\Omega_{\rho_{i}}} f^{n}(\mathbf{t}) g(\mathbf{t}) d \mathbf{t} & =\int_{\Omega_{\rho_{i}}}\left(\int_{[-n, n]^{m}} d \alpha(\mathbf{x}) \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}}\right) g(\mathbf{t}) d \mathbf{t} \\
& =\int_{[-n, n]^{m}} d \alpha(\mathbf{x}) \int_{\Omega_{\rho_{i}}} \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}} g(\mathbf{t}) d \mathbf{t} \\
& =\int_{[-n, n]^{m}} d \alpha(\mathbf{x}) R(\mathbf{x}, \rho) \tag{11}
\end{align*}
$$

From the last proposition we know that $\lim _{n \longrightarrow \infty} f^{n}(\boldsymbol{\omega})=f(\boldsymbol{\omega})$ uniformly. Moreover, since $g(\mathbf{t})$ is an absolutely integrable function it follows that $R(\mathbf{x}, \boldsymbol{\rho})$ is a uniformly continuous function. Hence

$$
\begin{equation*}
\lim _{n \longrightarrow \infty} \int_{\Omega_{\rho_{i}}} f^{n}(\mathbf{t}) g(\mathbf{t}) d \mathbf{t}=\int_{\Omega_{\rho_{i}}} f(\mathbf{t}) g(\mathbf{t}) d \mathbf{t} \tag{12}
\end{equation*}
$$

With this argument at hand, and from (11) we conclude that

$$
\begin{equation*}
\lim _{n \longrightarrow \infty} \int_{\Omega_{\rho_{i}}} f^{n}(\mathbf{t}) g(\mathbf{t}) d \mathbf{t}=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) R(\mathbf{x}, \boldsymbol{\rho}) \tag{13}
\end{equation*}
$$

From the last equality and from $\sqrt{12}$ we obtain

$$
\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) R(\mathbf{x}, \boldsymbol{\rho})=\int_{\Omega_{\rho_{i}}} f(\mathbf{t}) g(\mathbf{t}) d \mathbf{t}
$$

In addition, we have

$$
R(\mathbf{x}, \boldsymbol{\rho}) \longrightarrow \underset{\substack{\rho_{i} \longrightarrow \infty \\(i=1, \ldots, m)}}{ } \int_{\mathbb{R}^{m}} \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}} g(\mathbf{t}) d \mathbf{t}
$$

and hence, for any fixed $a_{i}$ it follows

$$
\begin{equation*}
\int_{\Omega_{a_{i}}} d \alpha(\mathbf{x}) R(\mathbf{x}, \boldsymbol{\rho}) \longrightarrow \underset{\substack{\rho_{i} \longrightarrow \infty \\(i=1, \ldots, m)}}{ } \int_{\Omega_{a_{i}}} d \alpha(\mathbf{x}) \int_{\mathbb{R}^{m}} \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}} g(\mathbf{t}) d \mathbf{t} \tag{14}
\end{equation*}
$$

For the sake of simplicity, in the considerations to follow we will often omit the argument and write simply $R$ instead of $R(\mathbf{x}, \boldsymbol{\rho})$. Since $R$ is uniformly bounded then there exists a positive constant $M$ so that $|R| \leq M$ for all real numbers $x_{i}$ and $\rho_{i}$. Without loss of generality, we will prove the case $m=2$ only. A direct computation shows that

$$
\begin{aligned}
I:=\mid & \int_{-\infty}^{-a_{1}} \int_{-\infty}^{-a_{2}} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R+\int_{-a_{1}}^{a_{1}} \int_{-\infty}^{-a_{2}} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R \\
& +\int_{a_{1}}^{\infty} \int_{-\infty}^{-a_{2}} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R+\int_{-\infty}^{-a_{1}} \int_{-a_{2}}^{a_{2}} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R \\
& +\int_{a_{1}}^{\infty} \int_{-a_{2}}^{a_{2}} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R+\int_{-\infty}^{-a_{1}} \int_{a_{2}}^{\infty} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R \\
& +\int_{-a_{1}}^{a_{1}} \int_{a_{2}}^{\infty} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R+\int_{a_{1}}^{\infty} \int_{a_{2}}^{\infty} d \alpha^{1}\left(x_{1}\right) d \alpha^{2}\left(x_{2}\right) R \mid .
\end{aligned}
$$

Therefore, we obtain

$$
\begin{aligned}
I & \leq M\left[\left|\alpha^{1}\left(-a_{2}\right)-\alpha^{1}(-\infty)\right|\left|\alpha^{2}\left(-a_{1}\right)-\alpha^{2}(-\infty)\right|\right. \\
& +\left|\alpha^{1}\left(-a_{2}\right)-\alpha^{1}(-\infty)\right|\left|\alpha^{2}\left(a_{1}\right)-\alpha^{2}\left(-a_{1}\right)\right|+\left|\alpha^{1}\left(-a_{2}\right)-\alpha^{1}(-\infty)\right|\left|\alpha^{2}(\infty)-\alpha^{2}\left(a_{1}\right)\right| \\
& +\left|\alpha^{1}\left(a_{2}\right)-\alpha^{1}\left(-a_{2}\right)\right|\left|\alpha^{2}\left(-a_{1}\right)-\alpha^{2}(-\infty)\right|+\left|\alpha^{1}\left(a_{2}\right)-\alpha^{1}\left(-a_{2}\right)\right|\left|\alpha^{2}(\infty)-\alpha^{2}\left(a_{1}\right)\right| \\
& +\left|\alpha^{1}(\infty)-\alpha^{1}\left(a_{2}\right)\right|\left|\alpha^{2}\left(-a_{1}\right)-\alpha^{2}(-\infty)\right|+\left|\alpha^{1}(\infty)-\alpha^{1}\left(a_{2}\right)\right|\left|\alpha^{2}\left(a_{1}\right)-\alpha^{2}\left(-a_{1}\right)\right| \\
& \left.+\left|\alpha^{1}(\infty)-\alpha^{1}\left(a_{2}\right)\right|\left|\alpha^{2}(\infty)-\alpha^{2}\left(a_{1}\right)\right|\right] \rightarrow a_{a_{1}, a_{2} \rightarrow \infty} 0 .
\end{aligned}
$$

Extending the last inequality to a total of $2^{m}$ terms $(m>2)$, and using (14) we get

$$
\lim _{a_{i} \longrightarrow \infty} \int_{\Omega_{a_{i}}} d \alpha(\mathbf{x}) R(\mathbf{x}, \boldsymbol{\rho})=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \int_{\mathbb{R}^{m}} \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}} g(\mathbf{t}) d \mathbf{t}
$$

From here and (13) we find

$$
\int_{\mathbb{R}^{m}} f(\mathbf{t}) g(\mathbf{t}) d \mathbf{t}=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \int_{\mathbb{R}^{m}} \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}} g(\mathbf{t}) d \mathbf{t}=(2 \pi)^{m} \int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \mathcal{F}^{-1}(g)(\mathbf{x})
$$

Making the change of variables $t_{i} \longrightarrow \omega_{i}-t_{i}(i=1, \ldots, m)$ in the definition of $g$ we finally find

$$
\int_{\mathbb{R}^{m}} f(\mathbf{t}) g(\boldsymbol{\omega}-\mathbf{t}) d \mathbf{t}=\int_{\mathbb{R}^{m}} d \alpha(\mathbf{x}) \int_{\mathbb{R}^{m}} \prod_{i=1}^{m} e^{e_{i} t_{i} x_{i}} g(\boldsymbol{\omega}-\mathbf{t}) d \mathbf{t}
$$

## 4 CONVOLUTION

In this section we introduce the definition of convolution of Clifford functions. The convolution is related to pairs of Clifford functions belonging to ( V ).

Definition 4.1. Let $\alpha, \beta: \mathbb{R}^{m} \longrightarrow C l_{0, m}$ belong to $(V)$. The convolution $\alpha \odot \beta$ of $\alpha$ and $\beta$ is the uniquely determined function $\gamma: \mathbb{R}^{m} \longrightarrow C l_{0, m}$ given by

$$
\begin{equation*}
\gamma=\alpha \odot \beta:=\int_{\mathbb{R}^{m}} \alpha(\mathbf{x}-\mathbf{y}) d \beta(\mathbf{y}) \tag{15}
\end{equation*}
$$

for every $\mathbf{x}, \mathbf{y} \in \mathbb{R}^{m}$.
We underline that due to the noncommutativity of the quaternionic product, $\alpha \odot \beta$ does not coincide with $\beta \odot \alpha$ in general. We notice that the function $\gamma$ given by $\sqrt{15)}$ is well defined since it obviously holds

$$
|\gamma(\mathbf{x})| \leq \int_{\mathbb{R}^{m}}|\alpha(\mathbf{x}-\mathbf{y})||d \beta(\mathbf{y})| \leq \delta \int_{\mathbb{R}^{m}}|d \beta(\mathbf{y})|<\infty
$$

Let $\alpha, \beta, \zeta$ be elements of $(V)$, and $\lambda$ a Clifford constant. In particular, the convolution retains the following properties:

1. $(\alpha \odot \beta) \odot \zeta=\alpha \odot(\beta \odot \zeta) ;$
2. $\alpha \odot(\beta \pm \zeta)=\alpha \odot \beta \pm \alpha \odot \zeta$;
3. $\lambda(\alpha \odot \beta)=(\lambda \alpha) \odot \beta, \quad(\alpha \odot \beta) \lambda=\alpha \odot(\beta \lambda)$;
4. $\lambda(\alpha \odot \beta) \neq \alpha \odot(\lambda \beta)$ in general.

Next we formulate the results of this section.
Proposition 4.2. If $\alpha$ and $\beta$ are elements of $(V)$ then the function $\gamma$ defined by (15) belongs to ( $V$ ).

Proof. Let $\mathbf{x}, \mathbf{z} \in \mathbb{R}^{m}$. Since $\alpha$ is a continuous function then for every $\epsilon>0$ there exists a real $\delta=\delta(\epsilon)>0$ such that

$$
|\alpha(\mathbf{x})-\alpha(\mathbf{z})|<\frac{\epsilon}{M}
$$

whenever $|\mathbf{x}-\mathbf{z}|<\delta$. The constant $M>0$ is chosen so that $\int_{\mathbb{R}^{m}}|d \beta(\mathbf{y})|=M$ for every $\mathbf{y} \in \mathbb{R}^{m}$. Hence, it holds

$$
|\gamma(\mathbf{x})-\gamma(\mathbf{z})|=\left|\int_{\mathbb{R}^{m}}(\alpha(\mathbf{x}-\mathbf{y})-\alpha(\mathbf{z}-\mathbf{y})) d \beta(\mathbf{y})\right|<\epsilon
$$

Consequently $\gamma$ is a continuous function in $\mathbf{x}$. Since $\mathbf{x} \in \mathbb{R}^{m}$ is arbitrarily chosen it follows that $\gamma$ is also continuous.

Proposition 4.3. Let $\alpha$ and $\beta$ be elements of $(V)$. If $\alpha \in L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)$ then it holds

$$
\|\gamma\|_{L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)} \leq M\|\alpha\|_{L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)}
$$

Proof. Let $\alpha$ and $\beta$ be any functions in $(V)$. A first straightforward computation shows that

$$
\begin{aligned}
\|\gamma\|_{L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)} & =\int_{\mathbb{R}^{m}}|\gamma(\mathbf{x})| d \sigma(\mathbf{x}) \\
& =\int_{\mathbb{R}^{m}}\left|\int_{\mathbb{R}^{m}} \alpha(\mathbf{x}-\mathbf{y}) d \beta(\mathbf{y})\right| d \sigma(\mathbf{x}) \\
& \leq \int_{\mathbb{R}^{m}}\left(\int_{\mathbb{R}^{m}}|\alpha(\mathbf{x}-\mathbf{y})| d \sigma(\mathbf{x})\right)|d \beta(\mathbf{y})| \\
& =M\|\alpha\|_{L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)} .
\end{aligned}
$$

In consequence, the following result holds:
Corollary 4.4. Let $\alpha, \beta$ and $\alpha^{n}$ be elements of $(V)$. If $\alpha, \alpha^{n} \in L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)$ then it holds

$$
\left\|\gamma^{n}-\gamma\right\|_{L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)} \longrightarrow 0
$$

when $n \longrightarrow \infty$, where $\gamma^{n}=\alpha^{n} \odot \beta$ and $\gamma=\alpha \odot \beta$.
Proof. From the previous proposition a direct computation shows that

$$
\left\|\gamma^{n}-\gamma\right\|_{L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)} \leq M\left\|\alpha^{n}-\alpha\right\|_{L^{1}\left(\mathbb{R}^{m} ; C l_{0, m}\right)}
$$

and from this follows our assertion.

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